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VOLATILITY FORECASTING WITH MIXED DATA SAMPLING

Master's Thesis

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MSC IN ACTUARIAL AND FINANCIAL MATHEMATICS
QUANTITATIVE FINANCE MAJOR

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Budapest, 2021

Acknowledgment

I would like to express my gratitude to my supervisor, István Barra, for the tremendous support, advices and patience during the thesis and for the knowledge I have learnt. Moreover, I would like to thank to Gábor Molnár-Sáska.

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Chapter 1

Introduction

Volatility forecasting has a vital role in risk management, derivative pricing, portfolio selection and other financial activities, which is not only useful for investment banks, but for retail investors. Generally these models are used to predict the absolute magnitude of returns. The volatility forecasting for a panel is legitimately important in practical applications, such as portfolio risk, portfolio with volatility constraint in which the portfolio must be adjust when the volatility exceed certain level. The panel is a bucket of assets where the parameters and the explanatory variables are common for each asset. There is a tremendous literature in the field of volatility forecasting. We will discuss various approaches that involve not only returns, but other explanatory variables. We will formulate their characteristic that they should satisfy.

In this thesis we will first present the single asset models, which are the Mixed Data Sampling (henceforth MIDAS), Generalized Autoregressive Conditional Heteroskedasticity (henceforth GARCH), GARCH-MIDAS and Exponentially Weighted Moving Average (henceforth EWMA) models with their specification, properties and parameter constraints. We attempt to keep models as parsimonious as it can be. After that, we are going to present these models panel version, where we tried to keep the parameter space tight.

The structure of the thesis is as follows: In Chapter 2, I am going to present every single model I implemented throughout the thesis. In this chapter, my main objective is to discuss the properties of the models, then show how to estimate them. Finally, the Monte Carlo experiment, which is not only a good experience in visualizing the estimated parameters from the simulation, but a test for the implementation. In Chapter 3, I am going to show the technical part of the implementation strategy and describe the trick we used for parameter estimations. In Chapter 4, I am going to introduce the predictive ability tests. In Chapter 5, I am going to demonstrate the empirical results visually and numerical. In this chapter, I am going to present the model specifications, which I used for volatility forecasting, then I provide all outcomes from the predictive ability tests. Finally, in Chapter 6, the thesis ends with the conclusion.

1.1 Literature Review

The Mixed Data Sampling regression models are introduced in the paper of Ghysels et al. [2004]. MIDAS regression models involve data sampled at different frequencies and usually tightly parameterized. The idea come from the situations where the explanatory variables are sampled at a higher frequency, as they pointed out, in empirical work the treatment of higher frequency data is the aggregation. After that, the estimation of the lower frequency data with standard regression. In the following years the MIDAS framework has developed and researched. For instance, Ghysels et al. [2005] investigate the trade-off between conditional variance and conditional mean of the stock market return and find that MIDAS can forecast better the stock market variance than GARCH estimators due to the flexibility of taking account of data sampled at various frequencies. Furthermore, Eric Ghysels [2006] investigate further the predictability of return volatility, where emphasized the approach three main attributes, namely, simplicity, robustness and parsimony. Ghysels et al. [2007] introduce several new specification of MIDAS, such as the stepfunctions. Clements and Galvão [2008] analyze the quarterly output growth from monthly indicators, as they show MIDAS approach is outstandingly useful to eliminate the need of choose the number of lagged values. Alper et al. [2008] compare a linear univariate MIDAS regression model with the GARCH(1, 1) model for equity return volatilities in several emerging and developed markets, they conclude that MIDAS can forecast better in more volatile markets. Santos and Ziegelmann [2014] employs a study on Brazilian capital market volatility forecasting using MIDAS approach. Moreover, Walther et al. [2019] use the MIDAS framework on cryptocurrency markets, where they investigate the advantage of exogenous drivers to predict volatility. Finally, Foroni et al. [2015] and Ghysels and Qian [2019] present MIDAS specifications, which can be estimated by OLS.

In financial econometrics, an immense amount of research papers have investigated the model of volatility consists of multiple components. Schwert [1989] study the relation between stock volatility, macroeconomic volatility and several other factors. More recently, a new class of component volatility model were introduced in Engle et al. [2013] which is the GARCH-MIDAS model. This model is especially useful to characterize the linkage between short-and long-term volatility components. Short-term volatility refers to the intradaily or daily volatility, in contrast with long-term, which refers to monthly or quarterly volatility. Many more research paper has published in the following years. For example, Asgharian et al. [2013] compare the GARCH-MIDAS model predictive ability with the traditional GARCH model. Conrad and Loch [2014] show that long-term volatility is driven by related to the state of economic and future business conditions. Wang and Ghysels [2015] study the model from a probabilistic and statistical perspective. Conrad et al. [2018] forecast Bitcoin volatility with the model and show it is superior to forecasts based on simple GARCH models. Conrad and Kleen [2019] compare GARCH-MIDAS with wide range of competitor models and the results suggest that the model is specially good at forecaste for longer time horizon. Finally, Xu et al. [2019] develop a modified GARCH-MIDAS model to investigate the usefulness of Google search index.

Chapter 2

Volatility Models

In this chapter we will describe all the models that we implemented and developed. First, I would like to start with the basic models, which include the MIDAS, GARCH and GARCH-MIDAS models, where we describe all the necessary changes and assumption for the modeling we made. In the models we relied on the existing papers about the topic and we tried to be consistent with them. On the other hand, there were some cases, where we modified them in order to suit for our available data. For instance, MIDAS is mainly used for high-frequency data, but we are lack of such data, so we adjust the specification for lower frequency data. The assumptions we imply are based on parsimoniousness, to make models under parameterized as possible and can be modified to panel version easily. In the following sections reflects to the way we implemented the models. The first subsection contains all the necessary specification and constraint for the models, meanwhile the second is about how to estimate the parameters and finally the Monte Carlo approaches to test our implementation.

2.1 MIDAS

The first appearance of MIDAS in the literature was Ghysels et al. [2004] paper, where they developed a model for data sampled at different frequencies. In this paper, they compare distributed lag models with the MIDAS regression. Moreover, they highlighted the applicability of this model in finance. The main objective of MIDAS is to avoid aggregating higher frequency data into lower frequency to be modeled with standard linear regression, so it applies a lag polynomial operator to capture the whole potential from the available data. The main focus in Ghysels et al. [2005] and Ghysels et al. [2007] was on volatility, where they examined several lag structures to be tight parameterized the model. We use the previously mentioned papers expressions to describe the MIDAS model.

Let y_t denote to the lower frequency dependent variable for $t = 1, \dots, T$ refers to a certain period (say, a month), within that period $x_t^{(m)}$ the higher frequency explanatory variable is sampled m times between this period (say, daily or $m = 22$). We want to describe the relationship between y_t

and $x_t^{(m)}$, in the sense of using lagged observations of $x_t^{(m)}$. The MIDAS regression is the following:

$$y_t = \beta_0 + \beta_1 B(L^{\frac{1}{m}}, \theta) x_t^{(m)} + \epsilon_t^{(m)} \quad (2.1)$$

where $B(L^{\frac{1}{m}}, \theta) = \sum_{k=0}^K B(k, \theta) L^{\frac{k}{m}}$, where $L^{\frac{k}{m}}$ is a lag operator such that $L^{\frac{1}{m}} x_t^{(m)} = x_{t-\frac{1}{m}}^{(m)}$ and K refers to the number of lagged values. The lag coefficients in $B(k, \theta)$ of the corresponding lag operator $L^{\frac{k}{m}}$ are parameterized as a function of a small-dimensional vector of parameters Θ . β_1 is a scale parameter for the lag coefficients. Next, we continue with the specification of the lag structure.

2.1.1 The specification of weighting scheme

The usage of finite polynomial operator is one of the key component of the MIDAS framework, so we present the three most commonly mentioned finite polynomials. Starting with the "Beta Lag", which is considered throughout the literature Ghysels et al. [2007], Engle et al. [2013], Ghysels and Qian [2019]. The Beta Lag involves two parameters, $\Theta = (\theta_1, \theta_2)$, and the parametrization is the following:

$$B(k, \theta_1, \theta_2) = \frac{f\left(\frac{k}{K}, \theta_1, \theta_2\right)}{\sum_{k=1}^K f\left(\frac{k}{K}, \theta_1, \theta_2\right)} \quad (2.2)$$

where

$$f(x, a, b) = \frac{x^{a-1}(1-x)^{b-1}\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \quad (2.3)$$

$$\Gamma(a) = \int_0^\infty e^{-x} x^{a-1} dx \quad (2.4)$$

The following figure will deonstrate how flexiable it is correspond to different parameters:

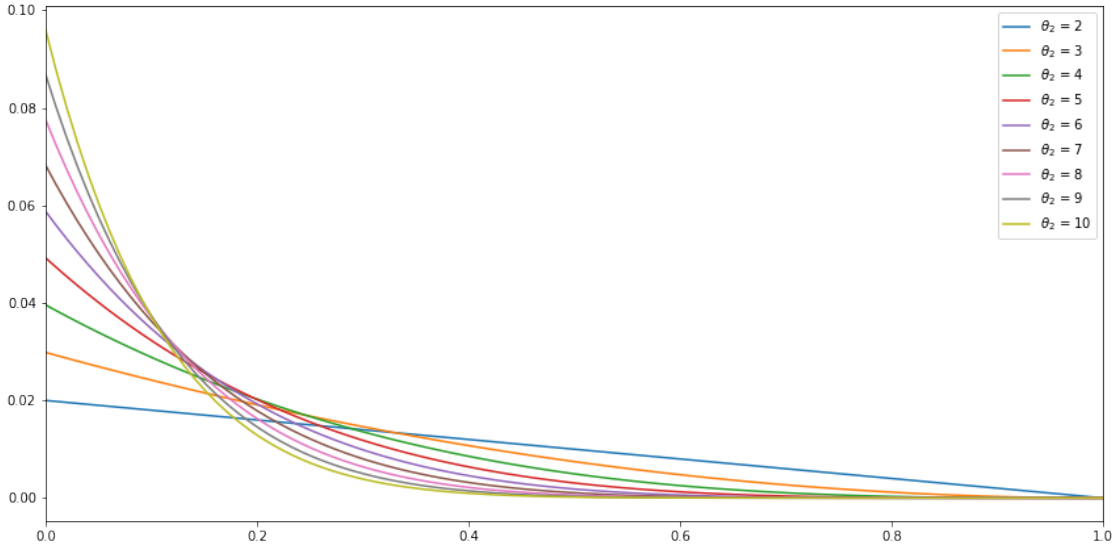


Figure 2.1: Plot of Beta Lag weighting function in equation (2) with $K = 100$, $\theta_1 = 1$ and $\theta_2 = 2, \dots, 10$

We can see that if we choose to fix $\theta_1 = 1$ and in the case of $\theta_2 > 1$ cause a monoton decliyin weighting structure. This weight function specification provide us positive coefficients, which is

crucial when we want to modeling volatility. The next polynomial specification is the "Exponential Almon Lag", where there are also two parameter to be used. It also shares the ability to be flexible as Beta Lag does. The specification is the following:

$$B(k, \theta_1, \theta_2) = \frac{e^{\theta_1 k + \theta_2 k^2}}{\sum_{k=1}^K e^{\theta_1 k + \theta_2 k^2}} \quad (2.5)$$

In the modeling, we found this specification fragile due to the scale of it's parameter throughout the optimization process.

Last, but not least we would like to present the exponentially weighted scheme which can be handy in the sense of there is only one parameter to be estimated. The weights are normalized to the sum be equal to 1:

$$B(k, \theta) = \frac{\theta^k}{\sum_{k=1}^K \theta^k} \quad (2.6)$$

2.1.2 Parameter Estimation

In this section I am going to describe the multivariate MIDAS parameter estimation. We can apply equation (2.1), but we can subtract N number of lagged explanatory variables from the dependent variable y_t . For the specification of polynomial lag operator we decided to use the so-called Beta lag. The parameter estimation happens through the mean squared estimate of error is as follows:

$$MSE = \frac{1}{T} \epsilon^T \epsilon = \frac{1}{T} \sum_{t=1}^T \left(y_t - \beta_0 - \sum_{n=1}^N \beta_n B(L^{\frac{1}{m}}, \theta_n) x_{t,n}^{(m)} \right)^2 \quad (2.7)$$

where the desired parameter set is $\Theta = (\beta_0, \beta_1, \dots, \beta_N, \theta_1, \dots, \theta_N)$ to be estimated. Since the MSE is a quadratic function we can find the optimal Θ parameter set by minimizing it:

$$\arg \min_{\Theta} MSE$$

2.1.3 Simulations

Not only serve as a test for our implementation, but also to see how precise is the estimation with certain sample sizes. The Monte-Carlo approach we present is originally from Conrad and Kleen [2019] to be able to check the consistency between the results. Let $X_{i,t}$ denote to be the high frequency explanatory variable for $t = 1, \dots, T$, where t represent the low frequency and $i = 1, \dots, I$ to be the intra steps and it is following an AR(1) process:

$$X_{i,t} = \phi X_{i-1,t} + \epsilon_t$$

where we set $\phi = 0.9, I = 22$ and assume $\epsilon_t \sim \mathcal{N}(0, 1)$ standard normal variable. Then the MIDAS equation will satisfy the following:

$$y_t = \beta_0 + \beta_1 \sum_{k=0}^K \xi_k(1.0, \theta) X_{i-k,t} + z_t$$

where we set $\beta_0 = 0.1, \beta_1 = 0.3$ and $\theta = 4$ and $z_t \sim \mathcal{N}(0, 1)$. The $\xi_k(1.0, \theta)$ represent the beta weighting scheme we used for simulation. We run the simulation on $T = \{96, 192, 382\}$, which

can be interpreted as 8, 16 and 32 years of data. The results are presented in the following figure, where we used the kernel density estimation method for receiving smoother histograms:

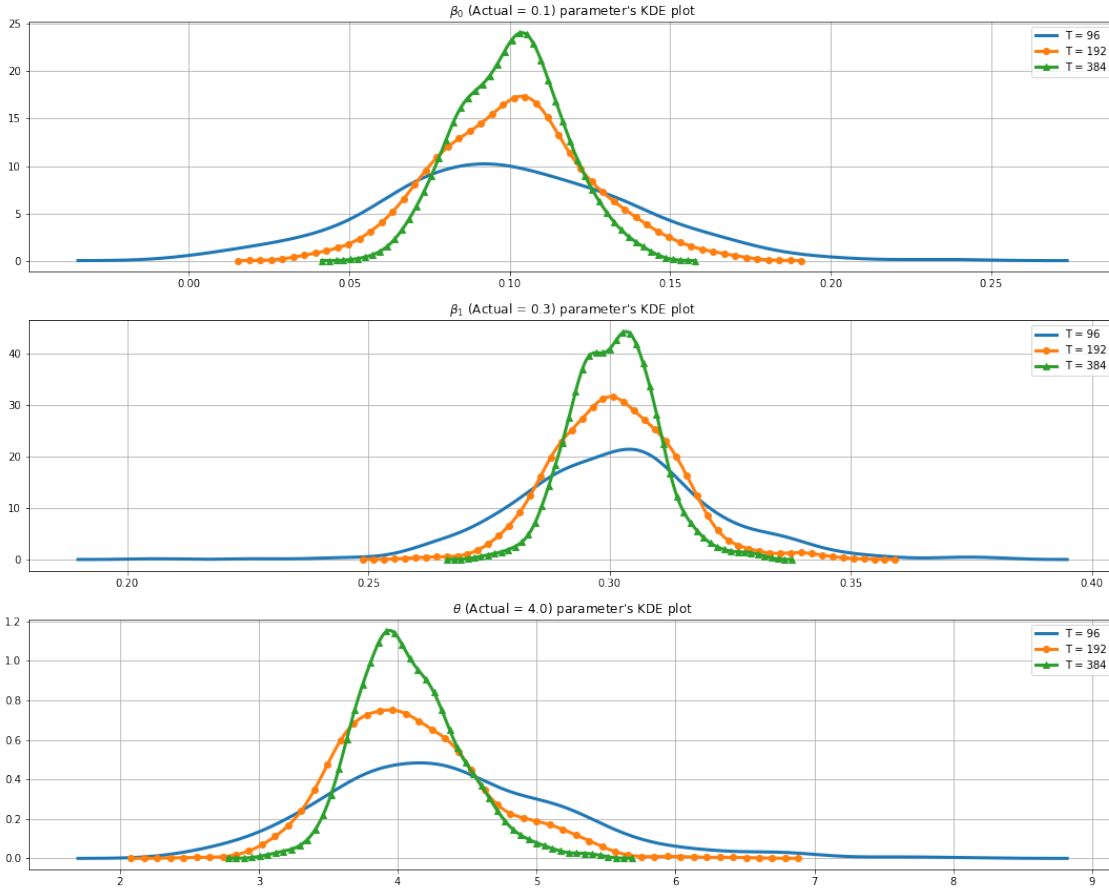


Figure 2.2: The estimated parameter distributions with sample sizes of 96, 192, 384

The simulation results met with our expectation, so the increment in the sample size reduces the uncertainty in the parameter estimations.

2.2 GARCH

In this section, I would like to give a brief overview about the GARCH model. The underlying concept was first developed in Engle [1982], the ARCH model, where we associated r_t with the daily log return ($r_t = \log P_t - \log P_{t-1}$, P_t is the stock price at time t) for $t = 1, \dots, T$, and assume that it can be written as $r_t = \mu_t \epsilon_t$, ϵ_t are modelled with ARCH model:

$$\epsilon_t = \sigma_t Z_t$$

$$\sigma_t^2 = \alpha_0 + \sum_{i=1}^p \alpha_i \epsilon_{t-i}^2$$

where the innovation Z_t are iid random variables with mean 0 and variance 1. Suppose $Z_t \sim \mathcal{N}(0, 1)$. The innovation's distribution can be modelled with various ways, such as Student-t distributed or, the most common, Normally distributed. The parameter constraints are: $\alpha_0 > 0, \alpha_i \geq$

This model was extended in Bollerslev [1986] to the Generalized ARCH model, where previous values of σ_t^2 are added to the volatility process. This development creates phenomenons that can be observed in markets, such as volatility clustering, where high volatility peroids tends to persist. The GARCH(1, 1) process is given by

$$\sigma_t^2 = \alpha_0 + \alpha_1 \epsilon_{t-1}^2 + \beta_1 \sigma_{t-1}^2$$

where ϵ_t are real-valued discrete-time stochastic process and \mathcal{F}_t is the information set of all information up to time t .

$$\epsilon_t | \mathcal{F}_{t-1} \sim \mathcal{N}(0, \sigma_t^2)$$

where $\alpha_0 > 0, \alpha_1 \geq 0, \beta_1 \geq 0$ and $1 > \alpha_1 + \beta_1$ is enough for wide-sense stacionarity.

$$E(r_t) = 0$$

$$Var(r_t) = E(r_t^2) - E(r_t)^2 = E(\sigma_t^2 Z_t^2) = E(\sigma_t^2) E(Z_t^2)$$

Since $Z_t \sim N(0, 1)$, so $E(Z_t^2) = 1$. Then,

$$E(\sigma_t^2) = E(\alpha_0 + \alpha_1 r_t^2 + \beta_1 \sigma_{t-1}^2) = \alpha_0 + \alpha_1 E(r_{t-1}^2) + \beta_1 E(\sigma_{t-1}^2)$$

From $r_t = \sigma_t Z_t$, it is known that $E(r_t^2) = E(\sigma_t^2)$ and for the process to be stationary $E(\sigma_t^2)$ must be a constant for all t :

$$E(\sigma_t^2) = E(\sigma_{t-1}^2) = E(r_{t-1}^2) = \sigma^2$$

the unconditional mean of the volatility process and the unconditional variance of the returns hence,

$$E(\sigma_t^2) = Var(r_t) = \frac{\alpha_0}{1 - \alpha_1 - \beta_1}$$

To examine the tail behavior we have to examine the excess kurtosis, which implies that the forth moment to exist and be finite. The excess kurtosis of r_t with normally distributed innovations is then

$$\begin{aligned} \frac{E(r_t^4)}{Var(r_t)^2} - 3 &= \frac{3(1 + \alpha_1 + \beta_1)\alpha_0}{(1 - \alpha_1 - \beta_1)(1 - 2\alpha_1^2 - (\alpha_1 + \beta_1)^2)(\frac{\alpha_0}{1 - \alpha_1 - \beta_1})^2} - 3 \\ &= 3 \frac{1 - (\alpha_1 + \beta_1)^2}{1 - 2\alpha_1^2 - (\alpha_1 + \beta_1)^2} - 3 \\ &= \frac{2\alpha_1^2}{1 - \alpha_1^2 - (\alpha_1 + \beta_1)^2} > 0 \end{aligned}$$

which means that r_t is fat-tailed, in other words extreme returns can be observed more frequently than they would with normally distributed innovations.

2.2.1 Parameter Estimation

We applied the Maximum Likelihood Estimation (henceforth MLE) for parameter estimation. In general, we assume an underlying distribution, which has some kind of probability density function, and we have θ the set of parameters to be estimated. In the assumption of normal distribution:

$$f(\epsilon_t | \theta) = \frac{1}{\sqrt{2\pi\hat{\sigma}_t^2(\theta)}} \exp\left(-\frac{\epsilon_t^2}{2\hat{\sigma}_t^2(\theta)}\right)$$

where ϵ_t are the innovations in GARCH type models, and $\hat{\sigma}_t^2(\theta)$ are the volatility estimates with given θ parameters. The loglikelihood function will be

$$\mathcal{L}(\theta) = f(\epsilon_1, \dots, \epsilon_T | \theta) = \prod_{t=1}^T \frac{1}{\sqrt{2\pi\hat{\sigma}_t^2(\theta)}} \exp\left(-\frac{\epsilon_t^2}{2\hat{\sigma}_t^2(\theta)}\right)$$

since the logarithm is a monotonically increasing function, the value which maximize the likelihood function will also maximize its logarithm as well. We can write a sum instead of a product in the log-likelihood function:

$$\log \mathcal{L}(\theta) = \frac{1}{T} \sum_{t=1}^T \left(\frac{1}{2} \log 2\pi + \frac{1}{2} \log \hat{\sigma}_t^2(\theta) + \frac{1}{2} \frac{\epsilon_t^2}{\hat{\sigma}_t^2(\theta)} \right) \quad (2.8)$$

The QMLE is then

$$\hat{\theta} = \arg \max_{\theta} \log \mathcal{L}(\theta) = \arg \min_{\theta} -\log \mathcal{L}(\theta) \quad (2.9)$$

In order to find the optimal parameter, we have to calculate with the negative loglikelihood function, since the optimization algorithms try to find the minimum of functions. Another usefully specification of the probability density function is the Student-t distribution. The log-likelihood of a Student-t distributed specification is the following:

$$\begin{aligned} \log \mathcal{L}(\theta) = & - \sum_{t=1}^T -\log \Gamma\left(\frac{\nu+1}{2}\right) + \log \Gamma\left(\frac{\nu}{2}\right) + \log \sqrt{2\pi(\nu-2)} + \frac{1}{2} \log \hat{\sigma}_t^2(\theta) \\ & + \frac{\nu+1}{2} \log \left(1 + \frac{\epsilon_t^2}{\hat{\sigma}_t^2(\theta)(\nu-2)} \right) \end{aligned}$$

2.2.2 Simulations

To ensure our implementation will truly estimate the desired parameters, we perform a Monte-Carlo simulation for the GARCH(1, 1) model with different sample sizes. In the simulation process we assume that, the log returns follow a normal distribution with the variance from the current state's σ_t^2 . The results from the simulations estimated by QMLE as it was described in the previously. Formally we can write as

$$\epsilon_t \sim \mathcal{N}(0, \sigma_t^2) \quad (2.10)$$

for $t = 1, \dots, T$, where T is the length of the sample size. The results of the parameter estimations is shown:

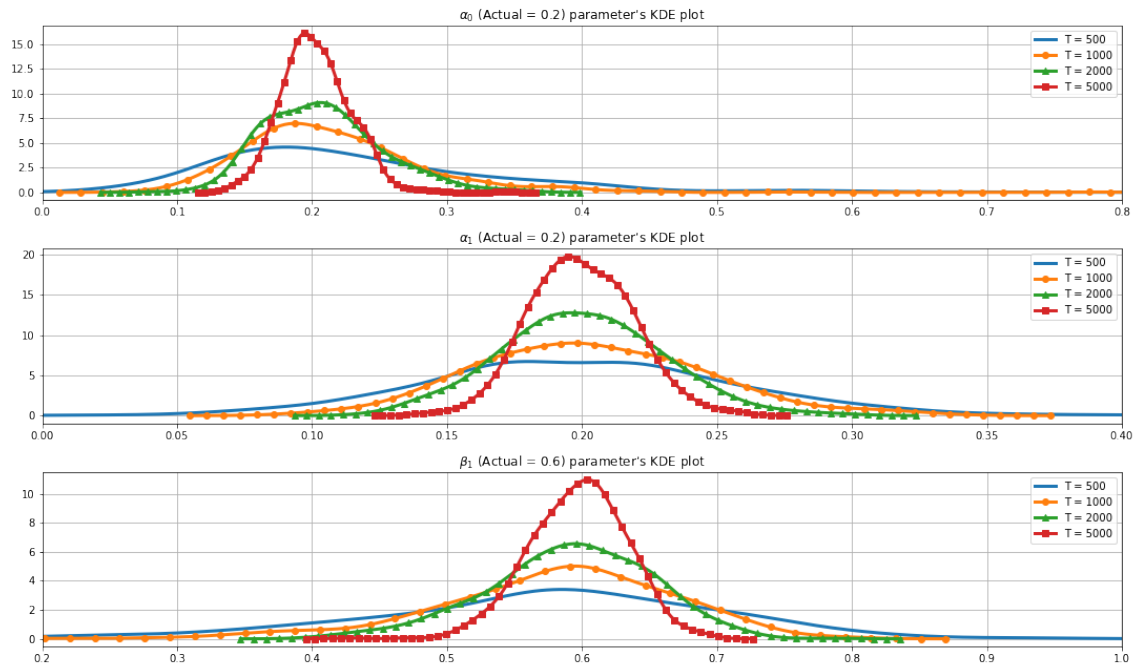


Figure 2.3: The estimated parameter distributions with sample sizes of 500, 1000, 2000, 5000

The parameter distributions are presented with Kernel Density Estimation (KDE) for the better visualization. The peaks of the distributions are in the theoretical values, moreover, we can see that as we increase the sample size, the more accurate will be the parameter estimations and decrease the variances of the parameters.

2.3 GARCH-MIDAS

In this section we present a new class of component GARCH model based on the MIDAS regression. This GARCH-MIDAS framework gives us the possibility to incorporate macroeconomic variables sampled at a different frequency. All macroeconomic variables will be in the specification of the long-term component.

Several papers have been published in the recent years about the topic of GARCH-MIDAS model. Engle et al. [2013] was one of the first to discuss about this model. They rely on long historical time series and examined what was the impact of adding economic variables to the GARCH model. Asgharian et al. [2013] used this framework to predict future volatility, they incorporate with a principal component approach as well to reduce the dimensions of the explanatory variables. To conduct their results they found that GARCH-MIDAS forecast volatility better than a GARCH model. In Conrad and Loch [2014] found that long-term financial volatility behaves counter-cyclically and certain macroeconomic variables help GARCH-MIDAS model to predict better the long-term volatility. Wang and Ghysels [2015] showed that GARCH-MIDAS model has fat-tailed marginal distribution.

The GARCH-MIDAS framework gives us the opportunity to incorporate macroeconomic vari-

ables sampled at a different frequency. In the recent years many studies showed the effectiveness of this approach, the only pitfall, we found, is the amount of underlying data that we provide for the algorithm. Let r_t be the daily log-returns, for $t = 1, \dots, T$ refers to certain period (say a month) and the index $i = 1, \dots, I_t$ (say days) within that period. We assume that the daily log-returns are following:

$$r_{i,t} = \epsilon_{i,t} = \sqrt{g_{i,t}\tau_t}Z_{i,t} \quad (2.11)$$

where $\epsilon_{i,t} | \mathcal{F}_{i-1,t} \sim \mathcal{N}(0, g_{i,t}, \tau_t)$ with $\mathcal{F}_{i-1,t}$ is the information set up to day $i-1$ of period t . $g_{i,t}$ denote to the short-term component of conditional variance and follows a unit-variance GARCH(1, 1) process:

$$g_{i,t} = \alpha_0 + \alpha \frac{\epsilon_{i-1,t}^2}{\tau_t} + \beta g_{i-1,t} \quad (2.12)$$

where $\alpha_0 > 0, \alpha \geq 0, \beta \geq 0$ and $1 > \alpha + \beta$ is enough for wide-sense stationarity. τ_t is defined as a function of the explanatory variables $X_t^{(m)}$, where m refers to the m -th explanatory variable. This will serve as the long-term component that varies at lower frequency. We specified with the MIDAS regression as

$$\tau_t = \sum_{m=1}^M \beta_m \sum_{k=0}^K \phi_k(1.0, \theta_m) X_{t-k}^{(m)} \quad (2.13)$$

where K is the lag parameter and ϕ_k refers to the weighting scheme, which we can specify and M is the number of explanatory variables we use. We chose the Beta weighting scheme such as most of the papers suggested. As we fixed the first parameter of the Beta weighting scheme to 1.0, then it will allow us to get monotonously declining or increasing weights, as it was showed in the MIDAS section. If we want to use explanatory variables that can take positive or negative values, we used the exponential specification of the τ_t

$$\tau_t = \exp \left(\sum_{m=1}^M \beta_m \sum_{k=0}^K \phi_k(1.0, \theta_m) X_{t-k}^{(m)} \right) \quad (2.14)$$

We tried to minimize the number of estimated parameters, so we changed the short-term volatility component's equation with a few assumptions.

$$E(r_{i,t}) = 0$$

$$Var(r_{i,t}) = E(r_{i,t}^2) - E(r_{i,t})^2 = E(r_{i,t}^2) = E(\sigma_{i,t}^2 Z_{i,t}^2)$$

where they are independent, since $Z_{i,t} \sim \mathcal{N}(0, 1)$, so the expected value of squared $Z_{i,t}$ is equal to 1. Then,

$$E(\sigma_{i,t}^2) = E(g_{i,t}\tau_t) = E(g_{i,t})E(\tau_t)$$

since we assumed that these two factors contribute for the underlying volatility process, namely, for $\sigma_{i,t}^2$. The other assumption, that we used, is the expected values of the macroeconomic variables is equal to 0, namely, $E(X_t^{(m)}) = 0$. Hence, the logarithm of τ has an expected value 0 and τ_t is equal to 1.

$$E(g_{i,t}) = E\left(\alpha_0 + \alpha \frac{\epsilon_{i-1,t}^2}{\tau_t} + \beta g_{i-1,t}\right) = \alpha_0 + \alpha E(g_{i-1,t}) + \beta E(g_{i-1,t})$$

From $r_{i,t} = \sigma_{i,t}Z_{i,t}$, it is known that $E(r_{i,t}^2) = E(\sigma_{i,t}^2)$ and as we see in the GARCH section the unconditional variance of the returns henceforth

$$E(\sigma_{i,t}^2) = Var(r_{i,t}) = \frac{\alpha_0}{1 - \alpha - \beta}$$

We used the moment matching to eliminate the α_0 parameters in the following way:

$$\hat{\mu} = \frac{1}{TI_t} \sum_{t=1}^T \sum_{i=1}^{I_t} r_{i,t}^2$$

then we can rewrite the short-term volatility equation:

$$g_{i,t} = \hat{\mu}(1 - \alpha - \beta) + \alpha \frac{\epsilon_{i-1,t}^2}{\tau_t} + \beta g_{i-1,t} \quad (2.15)$$

where we can implicitly characterize α_0 by $\hat{\mu}(1 - \alpha - \beta)$, so we recude the parameter space by one parameter.

2.3.1 Parameter Estimation

The GARCH-MIDAS estimation made by maximum likelihood estimation, where the underlying two volatility component's parameters are estimated by a single-step. It was neceserry to highlight the single-step estimation, because in the further sections we will introduce the two-step method, which worked better for us in panel models. The loglikelihood function, then

$$\log \mathcal{L}(\Theta) = -\frac{1}{TI_t} \sum_{t=1}^T \sum_{i=1}^{I_t} \left(\frac{1}{2} \log 2\pi + \frac{1}{2} \log (g_{i,t}\tau_t) + \left(\frac{\epsilon_{i,t}^2}{2g_{i,t}\tau_t} \right) \right) \quad (2.16)$$

$$\arg \min_{\Theta} \log \mathcal{L}(\Theta)$$

2.3.2 Simulations

In the simulations, we assumed that the long-term volatility component is generated from X_t an AR(1) process:

$$X_t = \psi X_{t-1} + u_t$$

where u_t is a random process with mean zero and variance h^2 and $X_0 = 0$. We set them to $\psi = 0.8$ and $h^2 = 0.3$. Hence,

$$\log(\tau_t) = 0.3 \sum_{k=0}^K \phi_k(1.0, 4.0) X_{t-k}$$

where we chose $\beta_1 = 0.3, \theta = 4.0$ and $K = 12$. In the short-term volatility component $\alpha = 0.1$ and $\beta = 0.8$. As we described above, the returns generated in the following way:

$$r_{i,t} \sim \mathcal{N}(0, g_{i,t}\tau_t)$$

The simulations ran in $T = 60, 120, 180$, in other words they can be interpreted as 5-year, 10-year or 15-year length of data. The main objective was to about to see the increase the accuracy and the decrease of the variance of the parameter estimation.

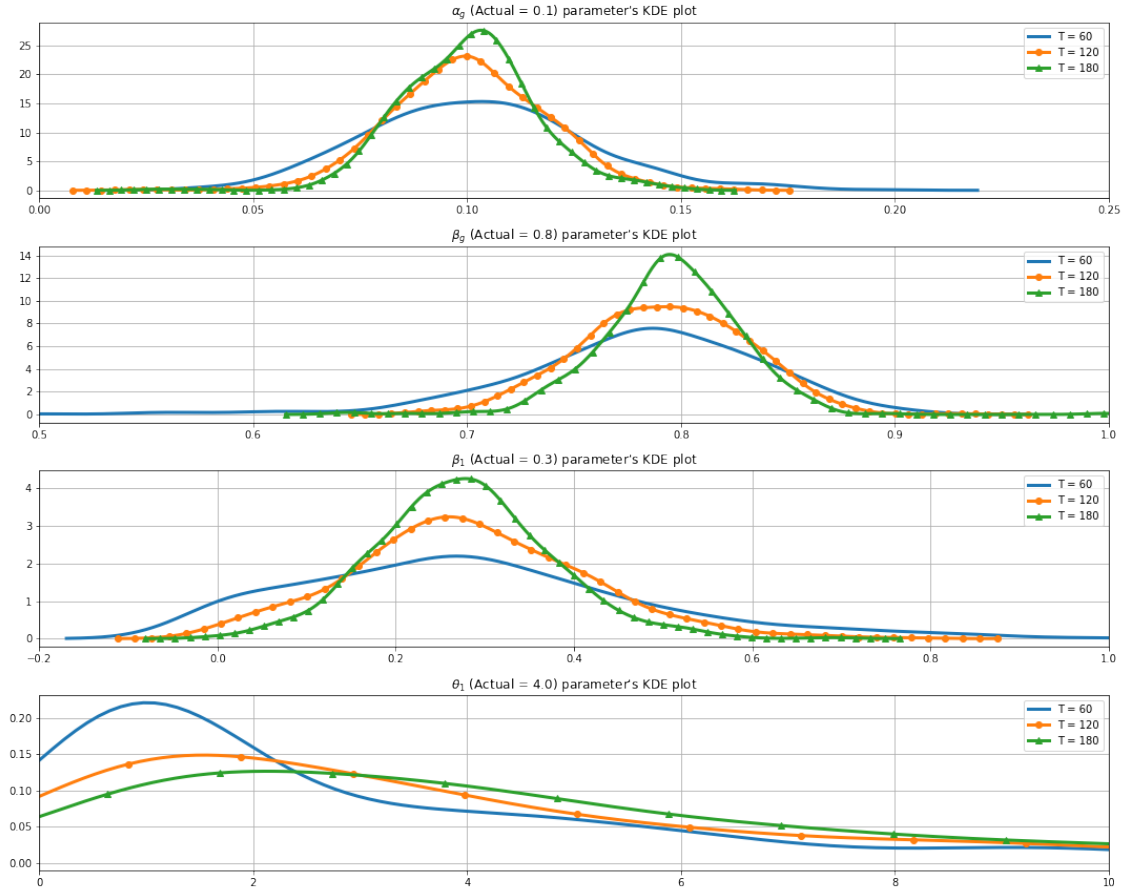


Figure 2.4: The estimated parameter distributions with sample sizes of $T = 60, 120, 180$

The α_0 , β_0 and β_1 median of distributions tend to converge to the theoretical values. Not only we can experience huge deviations in parameter's accuracy, but the θ estimated parameter's are not accurate at all. We conducted from these simulations, that we need to provide more data for this algorithm to excel in the parameter estimations, so in the following sections we will describe panel models.

2.4 Panel MIDAS

In this section I would like to introduce a new application of the MIDAS framework, namely, the panel version of the model. This approach not only provide better understanding about the underlying long term volatility, but it is parsimonious. The main idea was that there are a panel of stock returns and we would like to say something about the common long-term volatility component. In our application, we used the macroeconomic explanatory variables to model the volatility.

Let $r_{i,t,j}$ denote the j -th stock's daily return for $j = 1, \dots, N$, at i -th day for $i = 1, \dots, I_t$ of t -th month for $t = 1, \dots, T$. The indexes came from the GARCH-MIDAS section and we use the same symbols to be consistent. We assumed that these stocks share the same underlying volatility component that will be marked as τ_t . The long-term volatility component contains all

the explanatory variables, which can describe the volatility. If we choose $I_t = 1$ means we would like to calculate the monthly returns volatility, so both r and τ will be at the same frequency. Furthermore, we can apply weekly, daily or even intra daily explanatory variables in modeling the volatility. In the lack of intra day data and to keep the modeling as parsimonious as possible we used only monthly sampled data.

We describe τ_t as we did in GARCH-MIDAS section:

$$\tau_t = \sum_{m=1}^M \beta_m \sum_{k=0}^K \psi_k(1.0, \theta_m) X_{t-k}^{(m)} \quad (2.17)$$

where m refers to the m -th explanatory variable, K is the lag parameter and ϕ_k refers to the weighting scheme, which we can specify. We used the Beta weighting scheme for modeling as most of the papers suggested. We fixed the first paramter of the Beta weighting scheme to 1.0, then it will allow us to get monotoneously declining or increasing weights, as it was showed in the MIDAS section. We used the exponential specification of τ_t as we used explanatory variables which can take negative values:

$$\tau_t = \exp \left(\sum_{m=1}^M \beta_m \sum_{k=0}^K \phi_k(1.0, \theta_m) X_{t-k}^{(m)} \right) \quad (2.18)$$

2.4.1 Parameter Estimation

The Panel MIDAS model estimated by MLE that was described previously. We assumed that the stock's returns mean are equal to zero, then the negative loglikelihood function will be:

$$\log \mathcal{L}_j(\Theta) = -\frac{1}{T I_t} \sum_{t=1}^T \sum_{i=1}^{I_t} \left(\log 2\pi + \log \tau_t + \frac{(r_{i,t,j})^2}{\tau_t} \right) \quad (2.19)$$

The log likelihood of each individual stock is summed up to be minimized:

$$\arg \min_{\Theta} \sum_{j=1}^N \log \mathcal{L}_j(\Theta) \quad (2.20)$$

2.4.2 Simulations

The simulation was conducted in the spirit of MIDAS simulation with same changes. Let suppose we have one explanatory variable that define the volatility say X_t is an AR(1) process:

$$X_t = \psi X_{t-1} + \epsilon_t \quad (2.21)$$

where $t = 1, \dots, T$, $\psi = 0.9$ and $\epsilon_t \sim \mathcal{N}(0, 1)$ standard normal variable, than the MIDAS model will be:

$$\log \tau_t = \beta_1 \sum_{k=0}^K \phi_k(1.0, \theta) X_{t-k} \quad (2.22)$$

where $\beta_1 = 0.3$ and $\theta = 4.0$. τ_t remains the same throughout the whole period. The τ_t will determine the return's volatility, the returns are generated from normal distribution with zero mean and τ_t variance:

$$r_{i,t,j} \sim \mathcal{N}(0, \tau_t) \quad (2.23)$$

as τ_t is set to be a monthly variable, we generate daily return, so i mark mean that the i -th day of t -th month, $i = 1, \dots, I_t$, where $I_t = 22$ and j refers to the size of the panel.

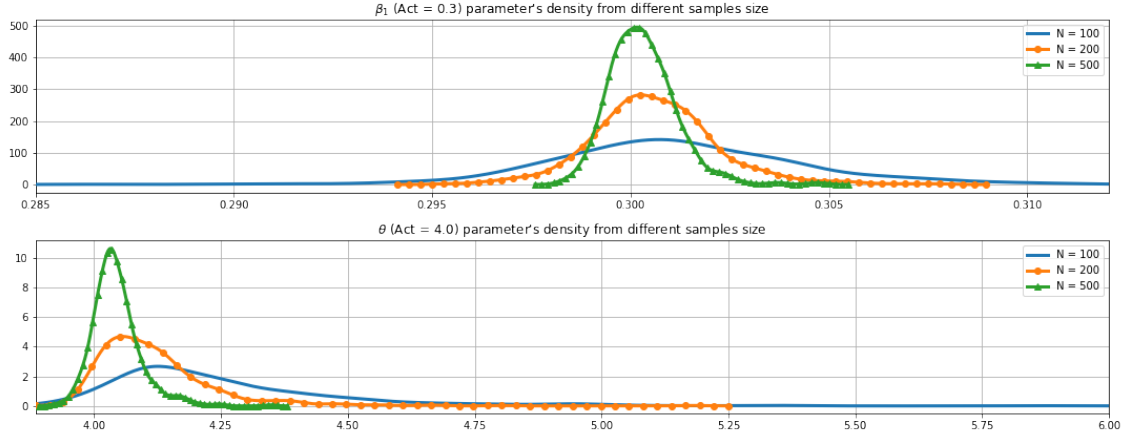


Figure 2.5: The estimated parameter distributions with sample sizes of $N = 100, 200, 500$

The distributions show that as we increase the panel size we get better parameter estimation. We simulated 100 month of data, which means around 2200 day's of returns. In the case of $N = 500$, we can say the model can estimate the parameters which we used for simulations.

2.5 Panel GARCH

In this section we would like to present the panel version of the GARCH model we described above. Our main goal was here to make the model as parsimonious as we could to become the benchmark model for our further analysis.

Let $r_{i,t,j}$ denote to the j -th stock's daily return for $j = 1, \dots, N$ at i -th day for $i = 1, \dots, I_t$ of t -th month for $t = 1, \dots, T$. In order to be consistent with the indexation, we decided to choose the ones that we used in Panel MIDAS section. Not only it will make easier to describe Panel GARCH-MIDAS model, but it also create consistency in indexes. We used the assumption of that the parameters for the dynamics of the volatilities are common to every stocks. In addition, the unconditional means of the volatilities are asset specific. The daily returns follow:

$$r_{i,t,j} = \epsilon_{i,t,j} = \sigma_{i,t,j} Z_{i,t,j} \quad (2.24)$$

where $Z_{i,t,j}$ the innovations which identiacally independent distributed random variables with mean 0 and variance 1. As we described in GARCH section, we specified the distributions for this innovation term, the first one is the Normal distribution and the other is the Student-t distribution to capture more extreme returns. The volatility equation can be written as:

$$\sigma_{i,t,j}^2 = \mu_j(1 - \alpha_1 - \beta_1) + \alpha_1 \epsilon_{i-1,t,j}^2 + \beta_1 \sigma_{i-1,t,j}^2 \quad (2.25)$$

where μ_j refers to the unconditional variance and the parameters of α_1 and β_1 satisfies $\alpha_1 \geq 0, \beta_1 \geq 0$ and $1 > \alpha_1 + \beta_1$ for wide-sense stacionarity. If we would like to estimate α and β for

each individual stock, we have to estimate $N + 2$ number of parameters. This can be challenging to estimate as the number of the assets increase, hence we assumed that the parameters in the volatility equations are common as we said earlier.

2.5.1 Parameter estimation

First of all we take advantage of the moment matching to calculate μ_j . Not only make it easier the estimation, but it will be more parsimonious. As μ_j is the unconditional variance of the returns, we can estimate by averaging the squared returns:

$$\hat{\mu}_j = \frac{1}{TI_t} \sum_{t=1}^T \sum_{i=1}^{I_t} r_{i,t,j}^2$$

In the second step given the unconditional variance estimates, the parameter space will reduce into just two parameter $\Theta = \alpha_1, \beta_1$. We used the MLE to minimize the negative log likelihood function given by:

$$\log \mathcal{L}_j(\Theta) = -\frac{1}{TI_t} \sum_{t=1}^T \sum_{i=1}^{I_t} \left(\frac{1}{2} \log 2\pi + \frac{1}{2} \log \sigma_{i,t,j}^2 + \frac{1}{2} \frac{\epsilon_{i,t,j}^2}{\sigma_{i,t,j}^2} \right) \quad (2.26)$$

where $\sigma_{i,t,j}^2$ is the function of the α_1, β_1

$$\arg \min_{\Theta} \sum_{j=1}^N \log \mathcal{L}_j(\Theta)$$

2.5.2 Simulations

We applied the same simulation scheme as we previously did in GARCH section. The only difference is we simulated matrix of returns. Here we sampled returns in arrays these are the rows in the matrix and in the end the columns mean the individual stock returns. As we simulated the returns we matched the individual volatility component which related to the desired "stock" return, so in each row every return has its unique variance.

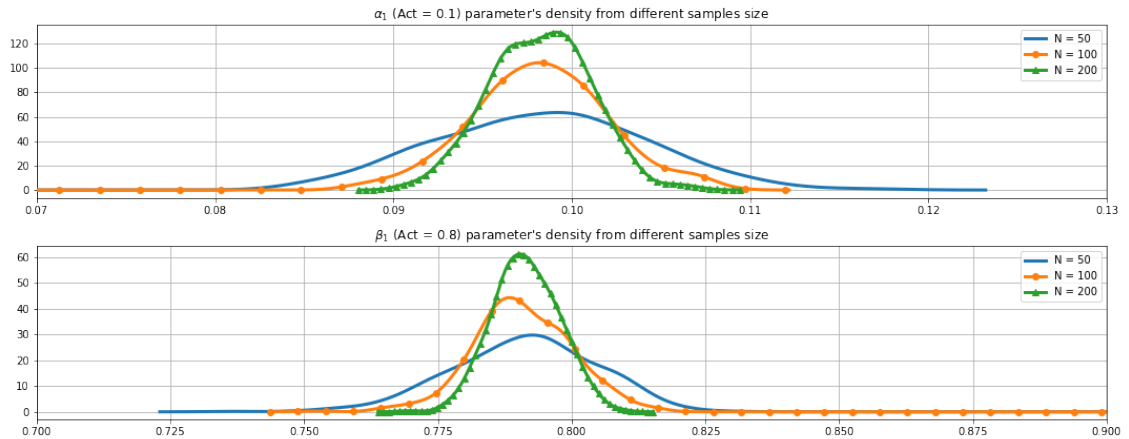


Figure 2.6: The estimated parameter distributions with sample sizes of 500 and $N = 50, 100, 200$

$$r_{i,t,j} \sim \mathcal{N}(0, \sigma_{i,t,j})$$

In the simulations we simulated panels with 50, 100, 200 number of individual stocks and 500 number of returns for each. In the above figure, we can see, as we increase the number of stocks in the panel the accurate will be the parameter estimations.

2.6 Panel GARCH with cross sectional adjustment

In this section, I would like to give you an overview of this unique model. The key concept of the model based on the cross sectional adjustment part, where we adjust the individual volatilities with the $c_{i,t}$ component. We used the same notations as we did in the Panel GARCH section, to be consistent and the reader can easily get familiar with the changes we made. Let $r_{i,t,j}$ denote the daily return of the j -th stock $j = 1, \dots, N$ at i -th day for $i = 1, \dots, I_t$ of t -th month for $t = 1, \dots, T$. The daily returns follow:

$$r_{i,t,j} = \sigma_{i,t,j} c_{i,t} \epsilon_{i,t,j} \quad (2.27)$$

where $\epsilon_{i,t,j}$ is the innovation, which identically independent distributed random variables with mean 0 and variance 1. The $c_{i,t}$ component is the cross sectional adjustment term, which can interpret as the common short-term volatility throughout the panel. Our theory for this particular term is when there are more and more abnormal returns in the panel, the $c_{i,t}$ component's value is rising. On the other hand, when the panel has a lower volatility period than it tends to decrease.

$$c_{i,t} = (1 - \phi) + \phi \sqrt{\frac{1}{N} \sum_{j=1}^N \left(\frac{r_{i-1,t,j}}{\sigma_{i-1,t,j} c_{i-1,t}} - \frac{1}{N} \sum_{j=1}^N \frac{r_{i-1,t,j}}{\sigma_{i-1,t,j} c_{i-1,t}} \right)^2} \quad (2.28)$$

where $1 \geq \phi \geq 0$ is the parameter of the adjustment. We can see if we observe ϕ equal to zero, then it is identically the same model with the Panel GARCH. This whole models lie on the $c_{i,t}$ last term, which is technically is the standard deviation of the innovations throughout the panel. The equation for $\sigma_{i,t,j}^2$ given by

$$\sigma_{i,t,j}^2 = \mu_j (1 - \alpha_1 - \beta_1) + \alpha_1 \epsilon_{i-1,t,j}^2 + \beta_1 \sigma_{i-1,t,j}^2 \quad (2.29)$$

where we applied the moment matching that we did in Panel GARCH section. The parameters of α_1 and β_1 satisfies $\alpha_1 \geq 0, \beta_1 \geq 0$ and $1 > \alpha_1 + \beta_1$

For illustration purposes, we would like to present the an estimated $c_{i,t}$ about a panel, which we will use in the modelling section:

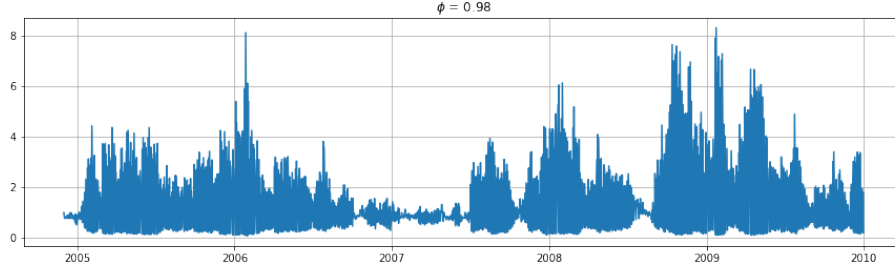


Figure 2.7: Plot of cross sectional adjustment component

In the above figure, we used a panel that consist of 492 stocks and the investigated period is between 2004-12-1 and 2009-12-31. You can clearly spot the higher volatility regimes in the plot.

2.6.1 Parameter estimation

As we mentioned in previously, we approximated the unconditional variance of the returns by averaging the squared returns. Moreover, we applied the same parameter estimation scheme for this model, namely the QMLE where the parameter space is then $\Theta = \phi, \alpha, \beta$. We assumed that the innovations are normally distributed, but as we would assume Student-t distribution, the parameter space would be expand with the parameter of the Student-t distribution's degree of freedom. We minimize the negative log likelihood function, which is given by:

$$\log \mathcal{L}_j(\Theta) = -\frac{1}{TI_t} \sum_{t=1}^T \sum_{i=1}^{I_t} \left(\frac{1}{2} \log 2\pi + \frac{1}{2} \log \sigma_{i,t,j}^2 + \frac{1}{2} \frac{\epsilon_{i,t,j}^2}{\sigma_{i,t,j}^2} \right) \quad (2.30)$$

$$\arg \min_{\Theta} \sum_{j=1}^N \log \mathcal{L}_j(\Theta)$$

2.6.2 Simulations

The simulations are made by a fairly simulare way, which we did in Panel GARCH. The returns are generated randomly from normal distribution with variance of $\sigma_{i,t,j}$:

$$r_{i,t,j} \sim \mathcal{N}(0, \sigma_{i,t,j}) \quad (2.31)$$

The $c_{i,t}$ component effect is take place in $\epsilon_{i,t,j}$. We simulated different size of simulated panels with the same sample size, $T = 500$. The parameters which we used for simulation purposes are $\phi = 0.9$, $\alpha_1 = 0.2$ and $\beta_1 = 0.6$. The results are the following:

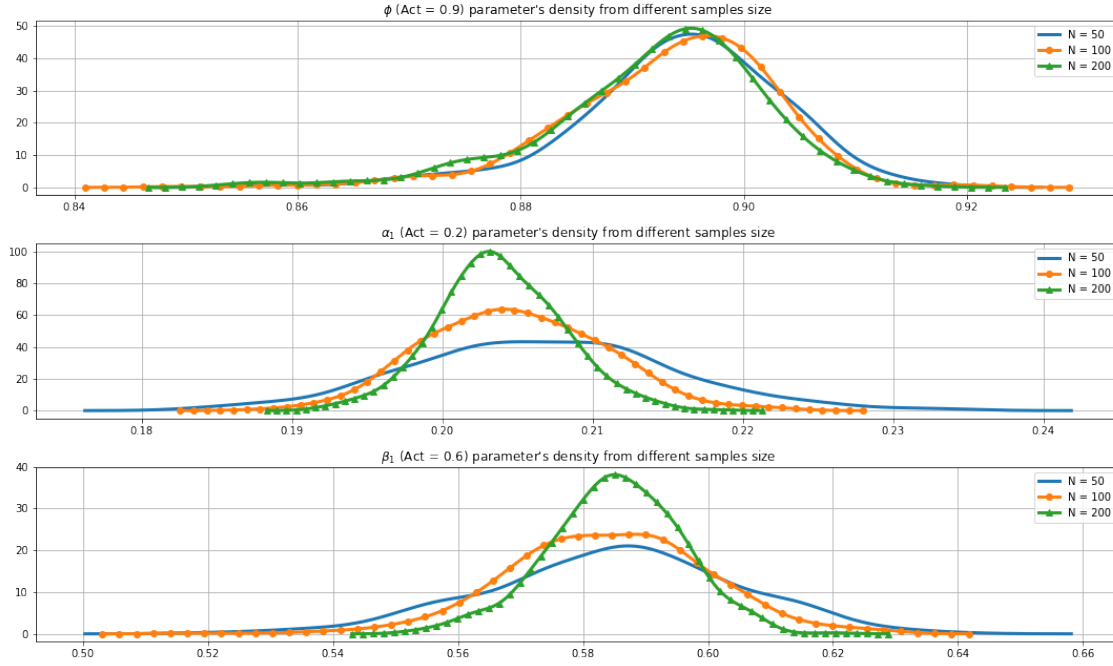


Figure 2.8: The estimated parameter distributions with $N = 50, 100, 200$

We can clearly see, as we increase the panel size, the lower the variance of the estimated parameters. Unfortunately, in the case of ϕ and β_1 the median estimated parameters are less, then what we used for simulations. In the case of α_1 the median estimation is higher. These miss estimation can be easily come from the relatively small sample size, the high α_1 and low β_1 . In the modeling section we will point out, this model required quite huge size of samples and the $\alpha_1 + \beta_1$ tend to be close to 1.0.

2.7 Panel GARCH-MIDAS

In this section we specify the Panel version of the GARCH-MIDAS model. During the implementation process of this model some issues arised such as identification issues in th estimation of parameters. Finally we decided that we will make a two-step estimation and combine the best of the two world namely Panel MIDAS and Panel GARCH. The implementation is design to handle both multiple asset and single assets, in order to compare the accuracy of parameter estimation with the original single-step GARCH-MIDAS model. The first step is to calculate the long-term volatility component by the Panel MIDAS model. Let $\tau_{i,t}$ to be:

$$\tau_{i,t} = \beta_0 + \sum_{m=1}^M \beta_m \sum_{k=0}^K \psi_k(1.0, \theta_m) X_{t-k}^{(m)} \quad (2.32)$$

where m refers to the $m - th$ explanatory variable, K is the lag parameter and ϕ_k refers to the weighting scheme. We used the exponentail specification of $\tau_{i,t}$ as we used explanatory variables

which can take negative values:

$$\tau_{i,t} = \exp \left(\beta_0 + \sum_{m=1}^M \beta_m \sum_{k=0}^K \phi_k(1.0, \theta_m) X_{t-k}^{(m)} \right) \quad (2.33)$$

The estimation will provide us the $\tau_{i,t}$, the i index refers to have the same length of the returns, but τ is constant between intra periods. With the long-term component we can rescale the returns, by dividing them with the square root of $\tau_{i,t}$:

$$\hat{r}_{i,t,j} = \frac{r_{i,t,j}}{\sqrt{\tau_{i,t}}} \quad (2.34)$$

This rescaled return will be modeled by Panel GARCH model to get the short-term volatility component. The daily rescaled log returns follow:

$$\hat{r}_{i,t,j} = \epsilon_{i,t,j} = \sigma_{i,t,j} Z_{i,t,j} \quad (2.35)$$

where $Z_{i,t,j}$ is the innovations, and we can rewrite this equation as the original literatures suggested if we replace the rescaled returns:

$$r_{i,t,j} = \sqrt{\tau_{i,t} \sigma_{i,t,j}^2} Z_{i,t,j} \quad (2.36)$$

where the returns are driven by the short- and long-term volatility components. Let's take a look at the short term volatility component's equation:

$$\sigma_{i,t,j}^2 = \mu_j(1 - \alpha - \beta) + \alpha \epsilon_{i,t-1,j}^2 + \beta \sigma_{i,t-1,j}^2 = \mu_j(1 - \alpha - \beta) + \alpha \frac{r_{i,t-1,j}^2}{\tau_{i,t-1}} + \beta \sigma_{i,t-1,j}^2 \quad (2.37)$$

where $\alpha \geq 0, \beta \geq 0$ and $1 > \alpha + \beta$.

2.7.1 Parameter Estimation

As we discussed, the estimation is a two-step QMLE estimation. In which we first optimize the parameter's of the long-term volatility component where assumed the normal distribution, then the negative log - likelihood function looks like:

$$\log \mathcal{L}(\Theta_1) = -\frac{1}{NTI_t} \sum_{j=1}^N \sum_{t=1}^T \sum_{i=1}^{I_t} \log 2\pi + \log \hat{\tau}_{i,t}(\Theta_1) + \frac{r_{i,t,j}^2}{\hat{\tau}_{i,t}(\Theta_1)} \quad (2.38)$$

In order to get the optimal parameters we minimize the argument's of the negative log likelihood

$$\arg \min_{\Theta_1} \log \mathcal{L}(\Theta_1)$$

Then in the case of short-term volatility component, we calculate with $\hat{r}_{i,t,j}$ the rescaled return, so

$$\log \mathcal{L}(\Theta_2) = -\frac{1}{NTI_t} \sum_{j=1}^N \sum_{t=1}^T \sum_{i=1}^{I_t} \log 2\pi + \log \hat{g}_{i,t}(\Theta_2) + \frac{\hat{r}_{i,t,j}^2}{\hat{g}_{i,t}(\Theta_2)} \quad (2.39)$$

This approach is slower in respect of take two optimization instead of one, but we found out that it can estimate the best parameters better in that case.

2.7.2 Simulations

This model basically used the same simulation framework, which we previously described in GARCH-MIDAS section. In the simulations, we assumed that the common long-term volatility component is generated from X_t an AR(1) process:

$$X_t = \psi X_{t-1} + u_t \quad (2.40)$$

where u_t is a random process with mean zero and variance h^2 and $X_0 = 0$. We set them to $\psi = 0.8$ and $h^2 = 0.3$. Hence,

$$\log(\tau_{i,t}) = 0.3 \sum_{k=0}^K \phi_k(1.0, 4.0) X_{t-k} \quad (2.41)$$

where we chose $\beta_1 = 0.3, \theta = 4.0$ and $K = 12$. In the short-term volatility component $\alpha = 0.06$ and $\beta = 0.8$.

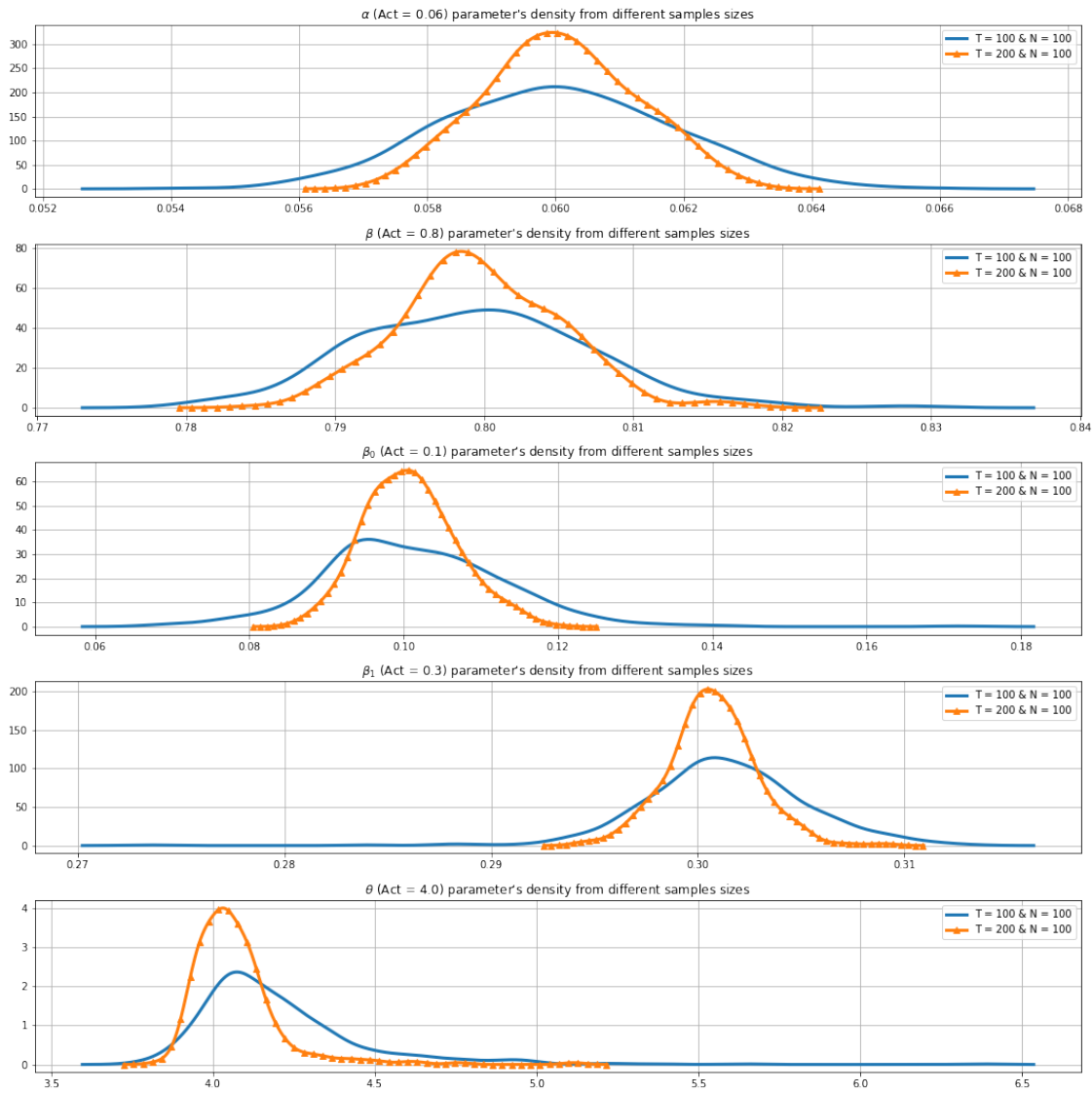


Figure 2.9: The estimated parameter distributions with sample sizes of 500 and $N = 50, 100, 200$

As we described above, the returns generated in the following way:

$$r_{i,t,j} \sim \mathcal{N}(0, g_{i,t,j} \tau_{i,t}) \quad (2.42)$$

The simulations ran in $T = 100, 200$, in other words they can be interpreted as 8-year, or 16-year length of data. The main objective was to about to see the increase the accuracy and the decrease of the variance of the parameter estimation.

In the the case of the first three parameters, we can see the expected tendency, what we waited for. Not only we can experinance huge deviations in parameter's accuary, but the θ estimated parameter's are not accurate at all. We conducted from these simulations, that we need to provide more data for this algorithm to excel in the parameter estimations, so in the following sections we will describe panel models.

2.8 Panel EWMA

In this section we present the industry standard volatility model, namely the Exponentially Weighted Moving Average (henceforth EWMA) model. In Morgan [1996] used EWMA with $\lambda = 0.94$. Let r_t denote to the daily log return ($r_t = \log P_t - \log P_{t-1}$, P_t is the stock price at time t) for $t = 1, \dots, T$. We assumed conditional normality for the distribution of returns r_t , with the volatility equation is the following

$$\sigma_t^2 = (1 - \lambda)r_{t-1}^2 + \lambda\sigma_{t-1}^2 \quad (2.43)$$

where λ is our only parameter to be estimated, which can only take $1 \geq \lambda \geq 0$. The above equation can be familiar with the one I described in GARCH section, this is not a coincidence. The EWMA is a special case of the GARCH model, namely the Integrated-GARCH (IGARCH), where we choose $\alpha_0 = 0, \alpha_1 = 1 - \lambda$ and $\beta_1 = \lambda$, so $1 = \alpha_1 + \beta_1$ which import a unit root to the GARCH process. For the unconditional variance of the returns we use the mean of the squared returns.

$$\hat{\sigma}^2 = \frac{1}{T} \sum_{t=1}^T r_t^2 \quad (2.44)$$

Let us describe the panel version of the EWMA model, where Let $r_{t,j}$ denote to the $j - th$ stock's daily return for $j = 1, \dots, N$ at time t for $t = 1, \dots, T$. We also assumed conditional normality for the distribution of returns $r_{t,j}$, with the volatility equation is the following

$$\sigma_{t,j}^2 = (1 - \lambda)r_{t-1,j}^2 + \lambda\sigma_{t-1,j}^2 \quad (2.45)$$

2.8.1 Parameter estimation

As I previously mentioned the only parameter we would like to estimate is λ , so the parameter space is $\Theta = \lambda$. We used the QMLE to minimize the negative log likelihood function given by:

$$\log \mathcal{L}_j(\lambda) = -\frac{1}{T} \sum_{t=1}^T \left(\frac{1}{2} \log 2\pi + \frac{1}{2} \log \sigma_{t,j}^2 + \frac{1}{2} \frac{\epsilon_{t,j}^2}{\sigma_{t,j}^2} \right) \quad (2.46)$$

where $\sigma_{t,j}^2$ is the function of the λ

$$\arg \min_{\Theta} \sum_{j=1}^N \log \mathcal{L}_j(\Theta)$$

2.8.2 Simulations

We applied the same simulation scheme as we previously did in Panel GARCH section. The returns are generated randomly from a normal distribution with variance $\sigma_{t,j}$:

$$r_{t,j} \sim \mathcal{N}(0, \sigma_{t,j}) \quad (2.47)$$

We simulated different size of simulated panels with the same sample size, namely $T = 500$. The parameter which we used for simulation purposes is $\lambda = 0.94$. The results are in the following figure:

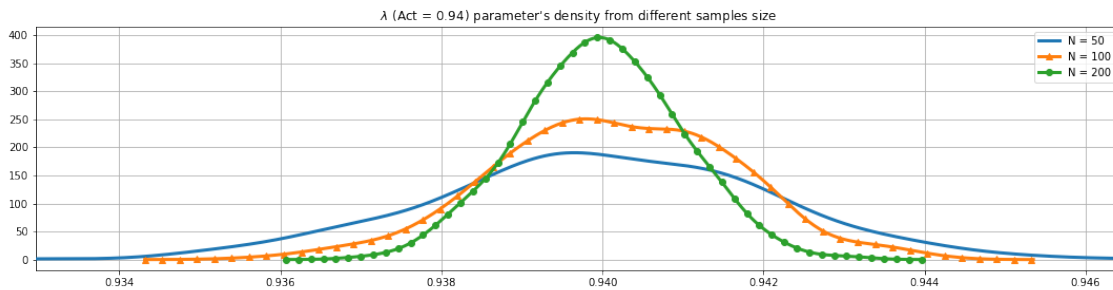


Figure 2.10: The estimated parameter distributions with $N = 100$ and the sample size is $T = 100, 200$

We can observe from the simulation results, that the increment of panel size reduce the variance of the parameter estimation.

Chapter 3

Implementation Strategy

In this chapter I am presenting the way we implemented, developed and tested our models. One of our objective was to not use the standard libraries, which befenit is the ability to modify and understand the models mechanism in a deeper level. First we declared a so-called metaclass, where we can define all the non-model specific functions. The metaclass is a class whose instances are classes in object-oriented programing. Not this approach provide clear script where we can debug more effectively, but we define new models in an straightforward way. In order to do that we relied on the Python's *abc* package to create the metaclass, which we denote to *Base*. For the choice of optimization algorithm we relied on the L-BFGS-B, which has a wide range of usage in machine learning. The L-BFGS-B algorith is in the family of quasi-Newton methods that uses the estimate of the inverse Hessian matrix to go through the parameter space. That feature of the algorithm is well suited take advantage of information matrix equality, so we can simply calculate the standard errors of the parameters with it.

One of the first issue we faced in the optimization process is the optimizer mishandling bounds and constraints. In order to avoid such failure of optimization, we implemented the so called parameter transformations

3.1 Parameter Transformation

In this section I am presenting the paraneter transformation approach to transform a constrained optimization problem into a unconstrained optimization. The main idea behind this strategy is that estimators can treat bounds, but in applications it is much more convenient to transform our parameters. With this approach we can create bounds without explicitly programming to the estimator function. First we describe the transform and the back-transform function, then show how they incopearte to the function that will be estimated. In our code these restrictions have to be desclared before the optimization process. Let θ denote to the parameter, we want to transform:

$$\tilde{\theta} = \begin{cases} \log(\theta) & \text{if 'pos' } \\ \log(\theta) - \log(1 - \theta) & \text{if '01' } \\ \theta & \text{otherwise} \end{cases}$$

$$\theta = \begin{cases} e^{\tilde{\theta}} & \text{if 'pos' } \\ \frac{1}{1+e^{-\tilde{\theta}}} & \text{if '01' } \\ \tilde{\theta} & \text{otherwise} \end{cases}$$

The 'pos' refers to parameters which can take values from the interval of $[0.0, \text{inf})$, as this parameter cannot be equal to zero we can take the log, so we transform to the interval of $(-\text{inf}, \text{inf})$. In other words, if we want a parameter to be strictly positive, we will apply this transformation and the restriction will stand throughout the optimization. In the case of '01' the parameters can only take values from $[0, 1]$ interval. This constraint is especially useful, when we estimate the GARCH model parameters. In the log likelihood function instead of calculating with the actual θ , the estimation will take place with $\tilde{\theta}$. Then the optimization finished, we can easily transform back. The only issue, which we had to handle was that the estimation of standard errors is not correct, so we implemented a function called *gradient*. In this function, you can see we calculated the first derivatives of the possible transformation. θ^* marked as the estimated parameters that were previously transformed.

$$gradient = \begin{cases} e^{\theta^*} & \text{if 'pos' } \\ \frac{e^{\theta^*}}{(1+e^{\theta^*})^2} & \text{if '01' } \\ 1 & \text{otherwise} \end{cases}$$

The above presented *gradient* function can treat the correction that come from the parameter transtion. This function plays a vital rule in the calculation of the standard errors of the estimated parameters, because without that our standard errors would be incorrect. In order to calculate the standard errors of the estimated parameters, now we can calculate their gradients, the inverse Hessian matrix was estimated throughout the optimization process, so we have to take the square root of the diagonal of the inverse Hessian and multiple by the gradients.

3.2 Model definition framework

In this section I am presenting the structure of the model definition framework, where I will define the rest of the functions. These functions are the minimum amount for creating new models, but we also implemented functions for simulation, prediction and other purposes.

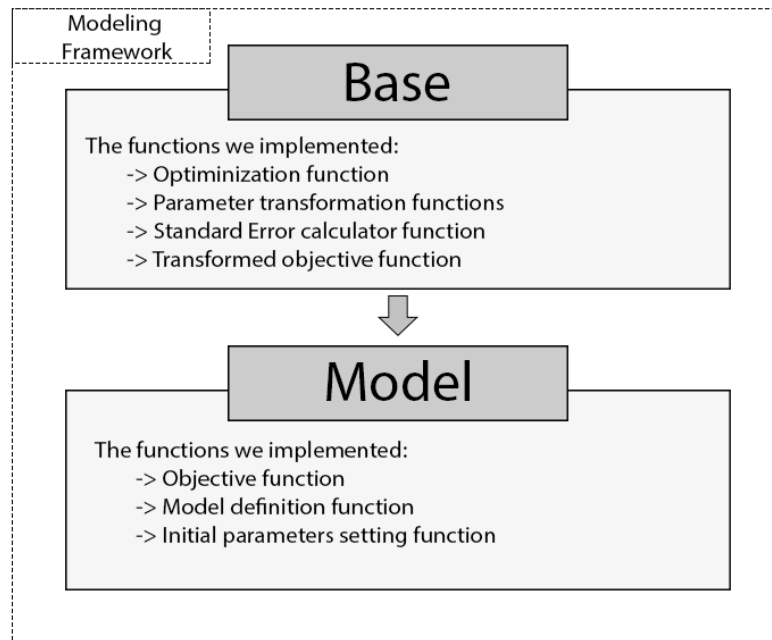


Figure 3.1: The model definition framework

In Figure 3.1 we can see how we defined certain parts of the model definition. As I described previously in this chapter, the main objective was to create a metaclass, where we define all the common functions. That is denoted with *Base*, meanwhile *Model* contains model specific functions. This class is unique for each and every model, so this mean all the model what we described in Chapter 2 are one-one model class. The optimization algorithms requires initial guesses for the parameters to be estimated, so we have to define an initial parameters setting function. These initial guesses are the starting points of the optimization, so it is crucial to find good ones. Some libraries imply basic estimation for such values to help algorithm converge to optimum faster. We didn't implemented such technique, so we relied on a trial-error scheme. In this we used the Monte Carlo approach to find robust initial values.

Chapter 4

Predictive Ability Tests

In this chapter I am going to present the most commonly used test to evaluate the volatility predictions. We mainly relied on previous research papers that used these methodologies for testing predicting capability. First, I am describing the Diebold-Mariano Test (henceforth DM Test), which was first developed by Diebold and Mariano [1995].

In the research of Conrad and Kleen [2019] refers to Patton [2011] paper about to compare the most commonly used loss functions for volatility forecast comparison. He found that there are only two robust loss functions, namely the mean squared error (MSE) and the QLIKE. He described the following family of loss functions, indexed by the scalar parameter b :

$$L(\hat{\sigma}^2, h; b) = \begin{cases} h - \hat{\sigma}^2 + \hat{\sigma}^2 \log \frac{\hat{\sigma}^2}{h} & , b = -1 \\ \frac{\hat{\sigma}^2}{h} - \log \frac{\hat{\sigma}^2}{h} - 1 & , b = -2 \\ \frac{1}{(b+1)(b+2)} (\hat{\sigma}^{2b+4} - h^{b+2}) - \frac{1}{b+1} h^{b+1} (\hat{\sigma}^2 - h) & , \text{otherwise} \end{cases}$$

In order to define different loss functions with only one parameter, namely with b , we implemented the above family of loss functions in our DM test. The author pointed out, the MSE loss function is obtained when $b = 0$ and the QLIKE when $b = -2$. These two function are the only robust ones, moreover the QLIKE is less sensitive with respect to extreme observation than the MSE loss. Meanwhile, QLIKE punishes more the assymmetric underestimation of loss. DM test relies on assumptions made directly on the forecast error loss differential Diebold [2015]. In DM test we compare two rival models, by taking there loss differences in the following way:

$$d_{12t} = L(\hat{\sigma}^2, h^{(1)}; b) - L(\hat{\sigma}^2, h^{(2)}; b) \quad (4.1)$$

where $\hat{\sigma}^2$ is the volatility proxy variable. Diebold [2015] presented that DM assumes:

$$DM = \begin{cases} E(d_{12t}) = \mu & , \forall t \\ cov(d_{12t}, d_{12(t-\tau)}) = \gamma(\tau) & , \forall t \\ 0 < var(d_{12t}) = \sigma^2 < \infty & , \text{otherwise} \end{cases}$$
$$DM = \frac{E(d_{12t})}{\sqrt{var(d_{12t})}} \sim \mathcal{N}(0, 1) \quad (4.2)$$

where $E(d_{12t})$ is the sample mean loss differential and $\sqrt{var(d_{12t})}$ is a consistent estimate of the standard deviation of d_{12t} .

The DM-test is a handy when we compare two forecasts for a single asset, what if we would like to compare two forecasts for panels. Timmermann and Zhu [2019] gave an approach us to do that. They developed new methods for testing forecasting powers in panels Let's start with the calculation of the mean loss throughout the whole panel, where we denote \bar{L}_m as

$$\bar{L}_h = \frac{1}{NT} \sum_{j=1}^N \sum_{t=1}^T L(\hat{\sigma}_t^{(j)^2}, h_t^{(j)}; b) \quad (4.3)$$

Their first hypothesis was that the panel's mean loss for a pair of forecasts, $h^{(1)}$ and $h^{(2)}$ is equal in expectation:

$$H_0^{panel} : E(\bar{L}_{h^{(1)}}) = E(\bar{L}_{h^{(2)}}) \quad (4.4)$$

In order to test the null hypothesis let's use the above defined d_{12t} , which is now a matrix and not an array, so the loss differential between forecasts $h^{(1)}$ and $h^{(2)}$ as

$$d_{12t} = L(\hat{\sigma}^2, h^{(1)}; b) - L(\hat{\sigma}^2, h^{(2)}; b) \quad (4.5)$$

We can test the null hypothesis in (37) using the test statistic

$$DM = (NT)^{-\frac{1}{2}} \frac{\sum_{j=1}^N \sum_{t+h=1}^T d_{12t}}{\hat{\sigma}(d_{12t})} \quad (4.6)$$

where $\hat{\sigma}(d_{12t})$ is a consistent estimator of standard deviation of d_{12t} .

Furthermore, we used the Mincer-Zarnowitz Regression Mincer and Zarnowitz [1969], which is basically a simple regression to be estimated:

$$\sigma_{t+1}^2 = \beta_0 + \beta_1 \hat{\sigma}_{t+1}^2 + \epsilon_t \quad (4.7)$$

where $\hat{\sigma}_{t+1}^2$ is the predicted value of the volatility for $t+1$. If the prediction is unbiased, then the coefficients are $\beta_0 = 0$ and $\beta_1 = 1$. We also investigate the R^2 aswell.

Another measure, what we investigated is the RMSE (root mean squared error)

$$RMSE = \sqrt{\frac{1}{NT} \sum_{j=1}^N \sum_{t=1}^T (\sigma_t^{(j)^2} - \hat{\sigma}_t^{(j)^2})^2} \quad (4.8)$$

where we can compare the RMSE values to eachother.

Chapter 5

Empirical Results

In this chapter, I am going to turn to the application of the above presented models. First, in Section 5.1 I introduce our data set, then I am going to present the estimated parameters for our models. Thereafter, in Section 5.2 I show our results from the RMSE, Mincer-Zarnowitz Regression and Panel version of Diebold Mariano Test. I am going to compare the models in the sense of the tests.

5.1 Descriptive Analysis

I use the Standard & Poor's 500 Index components for modeling purposes, which can be tricky, because in time several stocks come into the index and drop out. In order to avoid such problems like component changes, I decided to use those stocks which are in the S&P 500 Index at 2020/11/01. This fixation raised another issue in modeling, namely there are stocks in the panel, which didn't exist or cannot be observed properly in time. For example, Etsy, Inc. was introduced to S&P 500 Index at 2020/09/21 and it was first introduced to Nasdaq at 2015/04/16, so you cannot trade this particular stock before that period. Our solution is when you sum up the negative loglikelihood, you can skip those whose not exists. In the case of stocks that were introduced to the market during the investigated period, I add their negative loglikelihood to the sum where there was data. I also examined the case of drop out those stocks which have partial price history, it turned out no significant change arised.

First of all, I am going to present the models, which only involved stock returns. In this case I use two specifications of Panel GARCH model and a single for Panel EWMA and Panel GARCH with cross sectional adjustment model will be shown. The Panel GARCH models differ with respect to the definition of the underlying distribution. As I discussed earlier in GARCH section we can define the negative loglikelihood function with Normal and Student-t distributions, so in contrast them I use the "normal" and "student-t" notation to differentiate them.

Our estimations are based on a five year long training period, where I estimate the model parameters and forecast one-day ahead. The first training period was from 1999/12/01 to 2004/12/31,

then I shifted them by 1 month up until 2020/10/31. This shifting indicate 190 estimation and forecast for each and every models. In Figure 5.1 and Figure 5.2 we can observe the estimated parameters for Panel GARCH models in time. I would like to mention that I found quite interesting how β_1 decreases and α_1 increases after 2017.

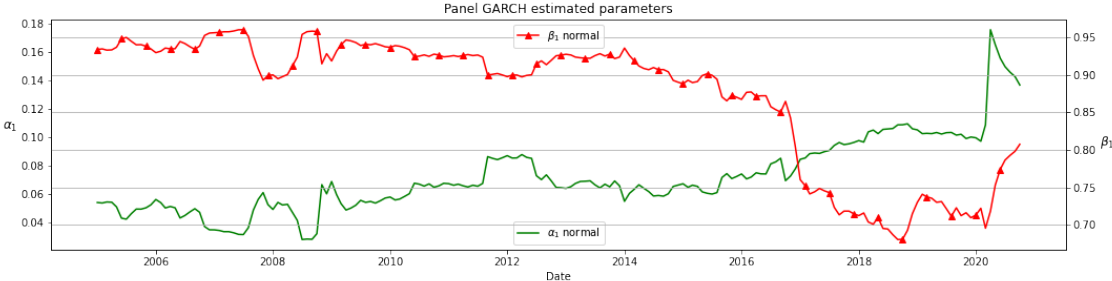


Figure 5.1: The estimated parameters for Panel GARCH (normal) model

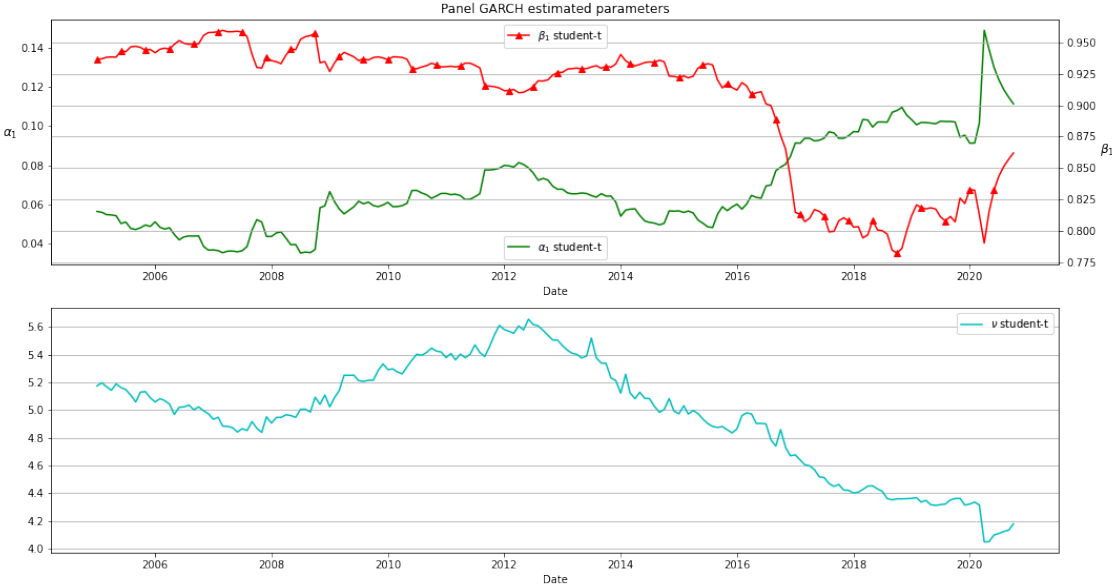


Figure 5.2: The estimated parameters for Panel GARCH (student-t) model

The first thing I investigate is to make sure this phenomenon arised from the increasing number of new stocks in the panel or not. I filter out the panel for stocks which have a full price history and estimate the parameters with them, then compare the results. I find that this phenomenon doesn't come from the increment in panel size. The other interesting observation is the ν parameter in Figure 5.2. The ν parameter is the degree of freedom or normality parameter in Student-t distribution. As ν increases, we get closer and closer to the normal distribution, in other word, the smaller the ν the fatter the tails, so more extreme return could happen. In the figure we can observe a tendency of decreasing ν after 2012 and a little plummet in 2020 when COVID hit the markets.

Let's turn into the Panel EWMA λ parameter. As I mentioned in Panel EWMA section we

can interpret λ as β and $1 - \lambda$ as α from the GARCH equation. In the case of high λ means the daily volatility respond relatively slowly to the daily return changes. On the other hand lower λ indicates that daily returns have a higher contribution for the volatility, so more volatility could be observed in the market

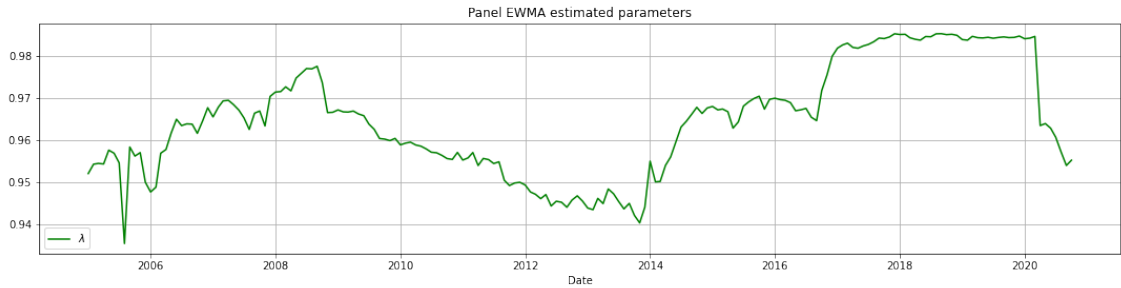


Figure 5.3: The estimated λ parameter for Panel EWMA

We can see that after the subprime crisis and the COVID crisis the λ starts to decrease sharply. Furthermore, we can observe an intense increase when we don't use stressed period anymore for training.

Finally, the Panel GARCH with cross sectional adjustment, where ϕ shows us the level of adjustment. In generally speaking the higher the ϕ , the more extreme daily returns could be captured in the market and vice versa.

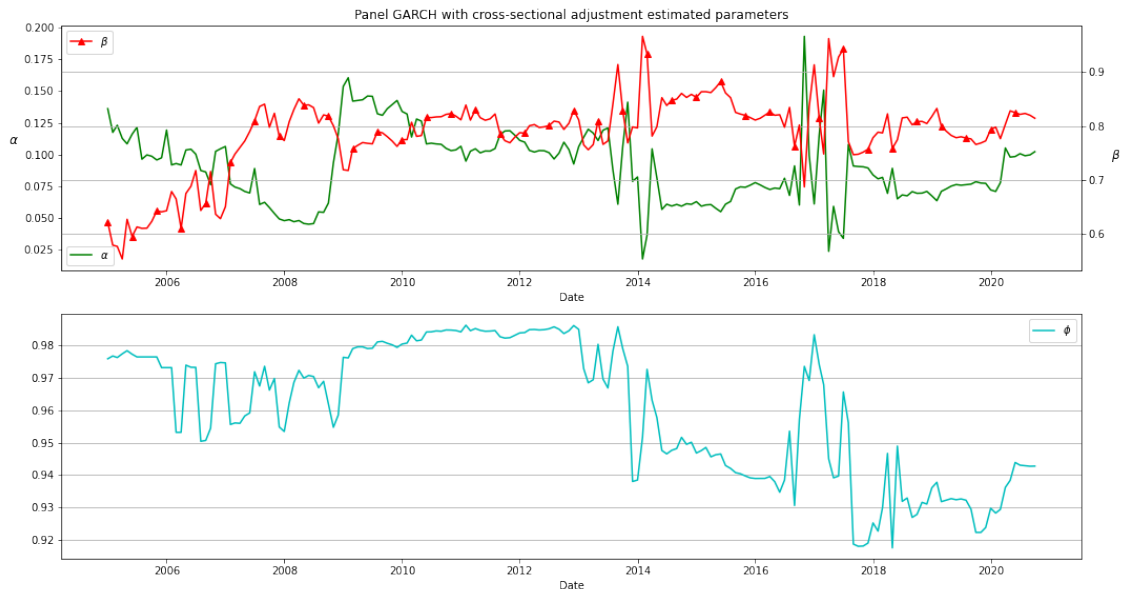


Figure 5.4: The estimated parameters for Panel GARCH with cross sectional adjustment

For this particular model the choice of training period is crucial. As the training data involves stressed period the ϕ remain relatively high, see the period between 2009 and 2013. We let this issue investigation for a further research.

Now, I am going to present the Panel GARCH-MIDAS model results. Most of the macroeco-

nommic time-series for modeling came from several research papers. You can read more about in Appendix A, where I describe all the time-series and their transformations. As I mentioned in Panel GARCH-MIDAS section I applied a two-stage estimation due to identification issues, so I was totally handy to run the second stage, namely the GARCH, on two specification, which I described above.

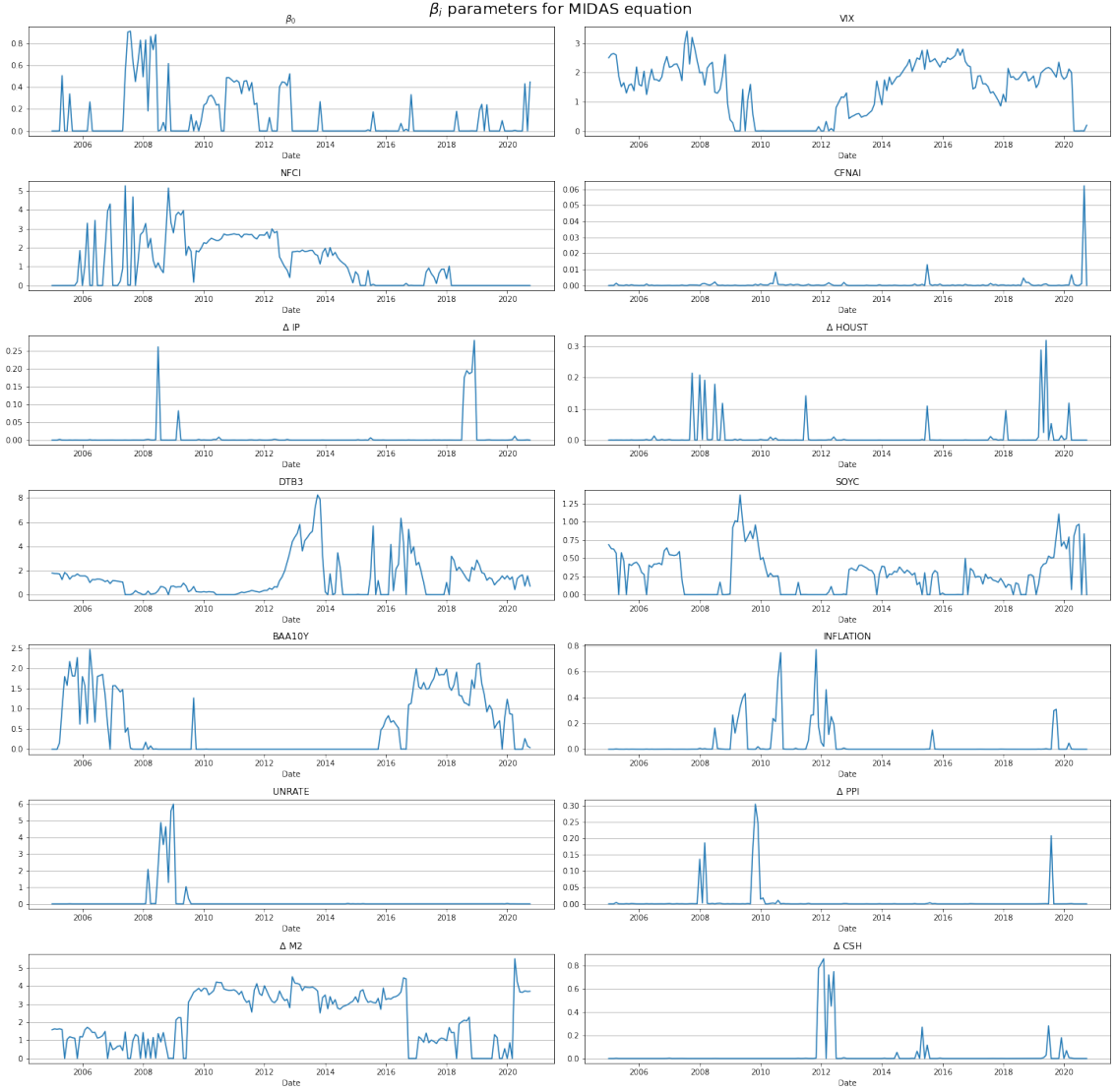


Figure 5.5: The estimated coefficients parameters for MIDAS equation in Panel GARCH-MIDAS

In Figure 5.5 we can see the estimated coefficients for the particular time-series. What I find impressive, how the certain macroeconomic variables play roles in periods. For instance, the VIX index has a really high contribution on low volatility regime, but it disappears in stressed periods. The following figure is going to present the lag coefficients.

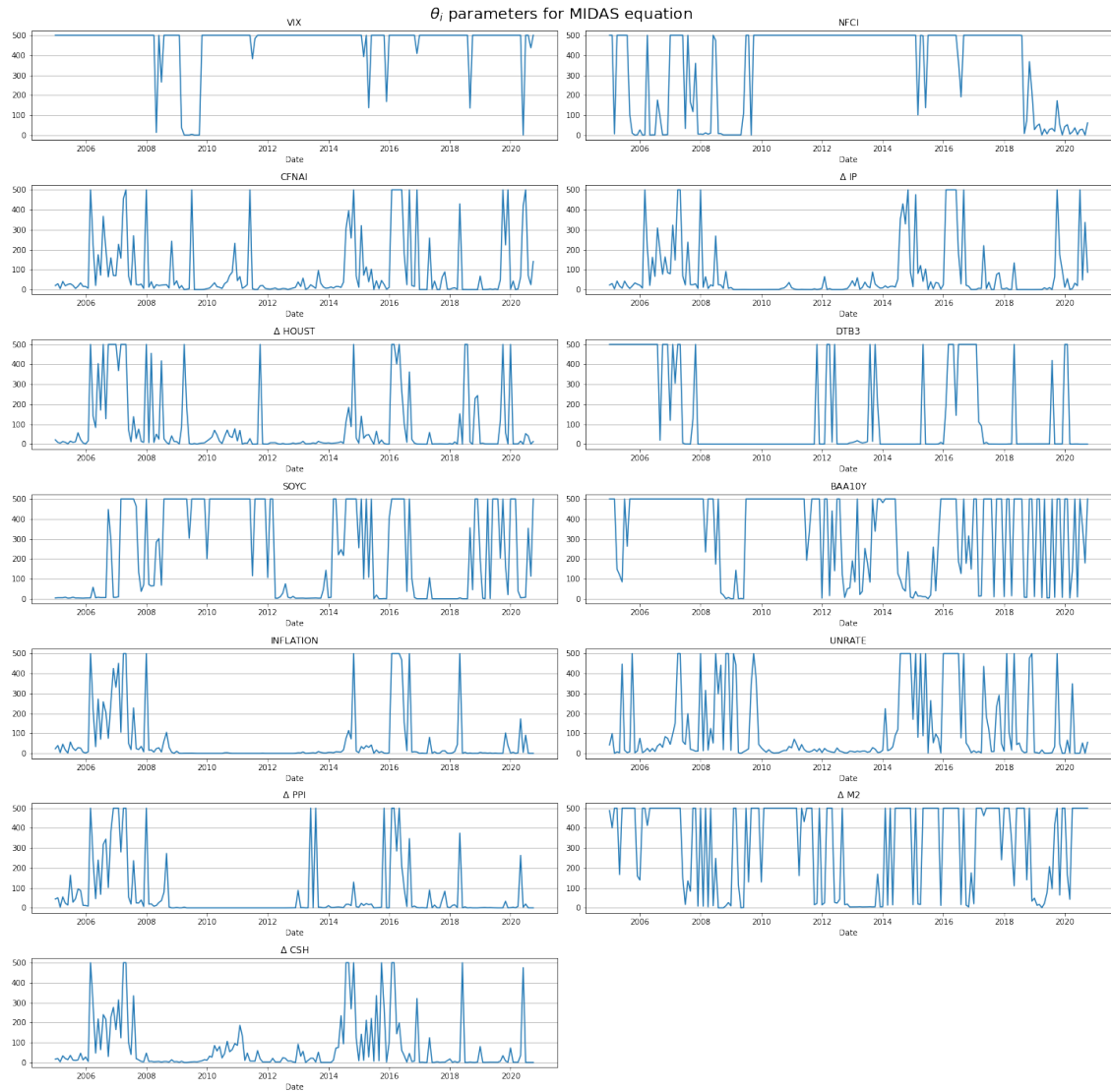


Figure 5.6: The estimated weighting parameters for MIDAS equation in Panel GARCH-MIDAS

The literature mainly rely on the Beta weighing scheme, so GARCH-MIDAS is specified with that. Figure 5.6 presents the estimated θ parameters for the weighing, where the first parameter sets to be 1.0 to make the parameter space as parsimonious as possible. In the optimization routine the only problem with this parameter is that it can go onwards to positive infinite, so the algorithm can estimate different parameters with the same underlying meaning. In other words, if we estimate θ to 1000 or 1 million, they will both return the same value. The eximination of θ parameter drives me to cap in the value of 500, because Beta weighting with $\{1.0, 500.0\}$ means the first observation get approximately one hounded percentage of weight and zero for the rest. In order word, the increment of θ after a certain value does not matter.

In the following two figures I am going to present the estimated GARCH parameters, for normally distribution assumption and Student-t. Let's start with the normally, where we can see the similar effect I describe in vanilla Panel GARCH model.

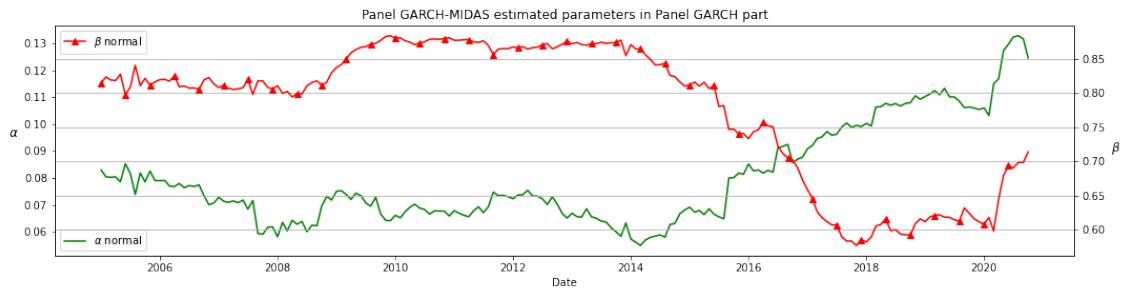


Figure 5.7: The estimated parameters for GARCH (normal) equation in Panel GARCH-MIDAS

I also investigate the panel size increment in this model as well and find that it has so little effect on the estimated parameters. What we observed in Panel GARCH with cross sectional adjustment model, the β starts to decrease and α increases as we drop out the stressed period. As I subtract the returns with the long-term volatility component, which come from the MIDAS part, we can see that the ν parameter is a bit upward shift than the unfiltered one. Moreover, we can also capture the same shrinkage in this parameter after 2013.

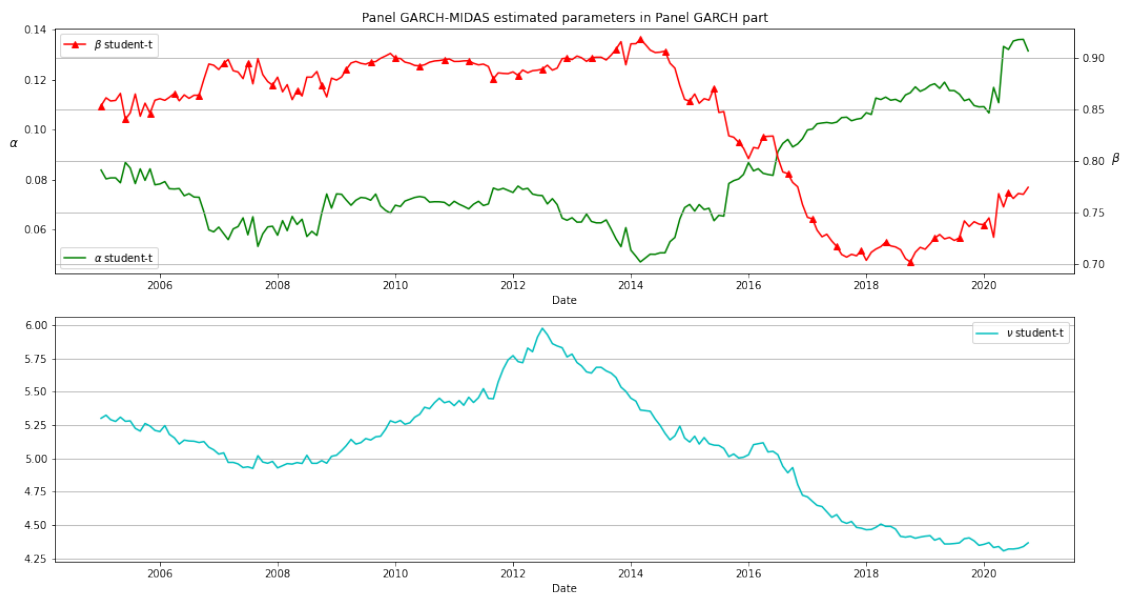


Figure 5.8: The estimated parameters for GARCH (student-t) equation in Panel GARCH-MIDAS

Table 5.1 provides summary statistics for the estimated parameters in the MIDAS part. While the table shows there are several variables that have absolutely little contribution for the long-term volatility, see $CFNAI$ or ΔPPI , where the coefficients are zeros up to 75 percent percentile. In the table we can see that the weighting parameter for the VIX variable is 500 most of the cases, so it would be more parsimonious if we just use the last observation.

	mean	std	min	25%	50%	75%	max
β_0	0.123	0.221	0.000	0.000	0.000	0.185	0.910
β_{VIX}	1.408	0.931	0.000	0.516	1.631	2.143	3.412
θ_{VIX}	465.062	119.194	0.005	500.000	500.000	500.000	500.000
β_{NFCI}	1.163	1.285	0.000	0.000	0.800	2.181	5.267
θ_{NFCI}	339.100	221.789	0.000	43.462	500.000	500.000	500.000
β_{CFNAI}	0.001	0.005	0.000	0.000	0.000	0.000	0.062
θ_{CFNAI}	88.756	152.055	0.000	4.645	20.172	69.518	500.000
$\beta_{\Delta IP}$	0.008	0.039	0.000	0.000	0.000	0.000	0.280
$\theta_{\Delta IP}$	74.894	140.399	0.001	0.592	15.074	64.989	500.000
$\beta_{\Delta HOUST}$	0.012	0.045	0.000	0.000	0.000	0.001	0.319
$\theta_{\Delta HOUST}$	89.362	162.229	0.000	1.672	9.590	69.569	500.000
β_{DTB3}	1.299	1.605	0.000	0.113	0.863	1.702	8.244
θ_{DTB3}	136.342	216.862	0.000	0.059	0.859	479.935	500.000
$\beta_{SOY C}$	0.278	0.287	0.000	0.000	0.250	0.416	1.366
$\theta_{SOY C}$	233.717	230.906	0.000	3.891	113.813	500.000	500.000
β_{BAA10Y}	0.544	0.735	0.000	0.000	0.001	1.153	2.470
θ_{BAA10Y}	340.812	210.839	0.000	120.335	500.000	500.000	500.000
$\beta_{INFLATION}$	0.038	0.118	0.000	0.000	0.000	0.001	0.770
$\theta_{INFLATION}$	58.145	132.918	0.000	0.139	3.351	28.239	500.000
β_{UNRATE}	0.168	0.836	0.000	0.000	0.000	0.000	5.992
θ_{UNRATE}	124.791	184.858	0.000	8.003	23.292	123.233	500.000
$\beta_{\Delta PPI}$	0.007	0.038	0.000	0.000	0.000	0.000	0.304
$\theta_{\Delta PPI}$	65.414	140.406	0.000	0.055	2.281	28.113	500.000
$\beta_{\Delta M2}$	2.192	1.476	0.000	0.999	2.270	3.576	5.505
$\theta_{\Delta M2}$	324.795	220.850	0.000	29.210	500.000	500.000	500.000
$\beta_{\Delta CSH}$	0.029	0.133	0.000	0.000	0.000	0.000	0.857
$\theta_{\Delta CSH}$	72.195	129.914	0.000	2.221	11.025	70.402	500.000

Table 5.1: The estimated parameters for MIDAS equation in Panel GARCH-MIDAS

5.2 Forecast Evaluation

In this section I am presenting the predictive ability test results. I am going to start with the root-mean squared error, then I turn into the Mincer-Zarnowitz regression for the different time horizon, where I compare the R^2 . Finally, the panel Diebold-Mariano test with MSE and QLIKE criteria for all the forecasting horizon. In the tables I marked the best models according to the particular test with a star.

Table 5.2 presents the RMSE results, where the Panel GARCH (student-t) model has the lowest score for 1-5 day ahead forecasting and Panel GARCH-MIDAS (student-t) come out the best for longer forecasting horizon, namely the 10-22 day ahead frame.

	Daily	Two daily	Weekly	Two weekly	Monthly
Panel GARCH (normal)	30.91	27.41	27.71	41.00	56.04
Panel GARCH (student-t)	30.86*	27.33*	27.46*	40.69	55.70
Panel GARCH-MIDAS (normal)	31.52	28.08	28.27	41.17	56.03
Panel GARCH-MIDAS (student-t)	31.07	27.58	27.60	40.61*	55.55*
Panel EWMA	31.11	27.52	27.64	40.81	55.74
Panel GARCH with cross sectional adjustment	32.87	29.63	31.17	44.53	59.55

Table 5.2: The table of RMSE results for all models and all forecasting horizons.

The Mincer-Zarnowitz Regression results show us the Panel GARCH (student-t) to be the best in all forecasting horizon. Conrad and Kleen [2019] agree that the R^2 of Mincer-Zarnowitz regression can be a misleading measure of forecast accuracy across volatility regimes.

	Intercept	Coefficient	R^2
Panel GARCH (normal)	-0.430	1.290	0.130*
Panel GARCH (student-t)	-0.040	1.200	0.130*
Panel GARCH-MIDAS (normal)	1.020	0.820	0.100
Panel GARCH-MIDAS (student-t)	0.490	0.940	0.120
Panel EWMA	0.260	1.120	0.120
Panel GARCH with cross sectional adjustment	2.600	0.720	0.020

Table 5.3: The table of Mincer-Zarnowitz Regression results for One-day ahead forecasting horizon for all models

Table 5.3 provides the results from the regressions and the R^2 , where the Panel GARCH models achieved the highest values, but they are still very low. Table 5.4 shows the two-day ahead forecasting regression coefficients and the R^2 start to increasing and the Panel GARCH models have the highest scores.

	Intercept	Coefficient	R^2
Panel GARCH (normal)	0.834	1.359	0.180*
Panel GARCH (student-t)	1.245	1.262	0.180*
Panel GARCH-MIDAS (normal)	2.447	0.850	0.126
Panel GARCH-MIDAS (student-t)	1.899	0.977	0.154
Panel EWMA	1.434	1.205	0.165
Panel GARCH with cross sectional adjustment	3.441	0.900	0.029

Table 5.4: The table of Mincer-Zarnowitz Regression results for Two-day ahead forecasting horizon for all models

	Intercept	Coefficient	R^2
Panel GARCH (normal)	1.626	1.967	0.343
Panel GARCH (student-t)	2.194	1.833	0.345*
Panel GARCH-MIDAS (normal)	4.201	1.189	0.223
Panel GARCH-MIDAS (student-t)	3.356	1.380	0.278
Panel EWMA	2.351	1.773	0.324
Panel GARCH with cross sectional adjustment	4.954	1.407	0.065

Table 5.5: The table of Mincer-Zarnowitz Regression results for One-week ahead forecasting horizon for all models

Table 5.5 and Table 5.6 show, for forecast horizons of one and two weeks the highest R^2 achieved by Panel GARCH (student-t), where the GARCH-MIDAS models start to drop behind and EWMA get closer.

	Intercept	Coefficient	R^2
Panel GARCH (normal)	2.852	2.719	0.332
Panel GARCH (student-t)	3.624	2.536	0.334*
Panel GARCH-MIDAS (normal)	6.442	1.637	0.214
Panel GARCH-MIDAS (student-t)	5.291	1.898	0.267
Panel EWMA	3.754	2.471	0.319
Panel GARCH with cross sectional adjustment	7.286	1.983	0.065

Table 5.6: The table of Mincer-Zarnowitz Regression results for Two-week ahead forecasting horizon for all models

	Intercept	Coefficient	R^2
Panel GARCH (normal)	5.935	3.540	0.327
Panel GARCH (student-t)	6.922	3.305	0.330*
Panel GARCH-MIDAS (normal)	10.741	2.108	0.206
Panel GARCH-MIDAS (student-t)	9.290	2.438	0.256
Panel EWMA	6.905	3.259	0.323
Panel GARCH with cross sectional adjustment	11.156	2.711	0.071

Table 5.7: The table of Mincer-Zarnowitz Regression results for One-month ahead forecasting horizon for all models

Finally, we consider the regression for one month ahead forecasting horizon, where the Panel GARCH (student-t) remains the best model according to the particular value. As we compare the R^2 scores with the root mean squared error the results are mixed, especially for longer horizon.

The following tables provides the results for the panel Diebold Mariano test, where we examine two test criteria, namely the MSE and QLIKE, which are the only robust ones Patton [2011].

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	0.894 (0.371)	-0.973 (0.331)	-0.414 (0.679)	-1.021 (0.307)	-1.395 (0.163)
Panel GARCH (student-t)		-0.99 (0.322)	-0.519 (0.604)	-1.041 (0.298)	-1.39 (0.165)
Panel GARCH-MIDAS (normal)			1.34 (0.18)	0.604 (0.546)	-0.929 (0.353)
Panel GARCH-MIDAS (student-t)				-0.087 (0.931)	-1.153 (0.249)
Panel EWMA					-1.452 (0.147)

Table 5.8: The table of Panel Diebold-Mariano Test results for One-day ahead forecasting horizon with MSE criteria

Table 5.8 and Table 5.9 shows, for forecast horizons of one day. Table 5.8 provide the results with MSE, which is more permissive criteria, so according to that all the models have the same predictive power. On the other hand QLIKE is less consessive, as Table 5.9 shows, in which GARCH (normal) and GARCH-MIDAS (normal) are better than EWMA and almost every model better the GARCH with cross sectional adjustment model.

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	-1.923 (0.055)	0.28 (0.779)	-0.302 (0.763)	-1.994* (0.046)	-2.5* (0.012)
Panel GARCH (student-t)		1.184 (0.237)	0.785 (0.432)	-1.714 (0.087)	-2.251* (0.024)
Panel GARCH-MIDAS (normal)			-1.711 (0.087)	-2.108* (0.035)	-2.521* (0.012)
Panel GARCH-MIDAS (student-t)				-1.916 (0.055)	-2.361* (0.018)
Panel EWMA					-1.756 (0.079)

Table 5.9: The table of Panel Diebold-Mariano Test results for One-day ahead forecasting horizon with QLIKE criteria

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	1.418 (0.156)	-0.926 (0.354)	-0.4 (0.689)	-0.715 (0.474)	-1.581 (0.114)
Panel GARCH (student-t)		-0.983 (0.326)	-0.559 (0.576)	-0.913 (0.361)	-1.582 (0.114)
Panel GARCH-MIDAS (normal)			1.358 (0.175)	0.727 (0.468)	-1.047 (0.295)
Panel GARCH-MIDAS (student-t)				0.106 (0.916)	-1.315 (0.189)
Panel EWMA					-1.677 (0.093)

Table 5.10: The table of Panel Diebold-Mariano Test results for Two-day ahead forecasting horizon with MSE criteria

Table 5.10 and Table 5.11 shows, for forecast horizons of two day. Table 5.10 provides the results with MSE, where there is not a single model significantly better than the other. Table 11 shows the results with QLIKE in which the GARCH-MIDAS (normal) turn out to be the best model.

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	-4.21* (0.0)	0.405 (0.686)	-0.699 (0.484)	-3.213* (0.001)	-2.42* (0.016)
Panel GARCH (student-t)		2.16* (0.031)	1.171 (0.242)	-2.3* (0.021)	-1.934* (0.053)
Panel GARCH-MIDAS (normal)			-4.102* (0.0)	-3.445* (0.001)	-2.417* (0.016)
Panel GARCH-MIDAS (student-t)				-2.768* (0.006)	-2.112* (0.035)
Panel EWMA					-1.261* (0.207)

Table 5.11: The table of Panel Diebold-Mariano Test results for Two-day ahead forecasting horizon with QLIKE criteria

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	1.768 (0.077)	-1.077 (0.282)	0.414 (0.679)	0.311 (0.756)	-1.689 (0.091)
Panel GARCH (student-t)		-1.266 (0.206)	-0.468 (0.64)	-0.612 (0.541)	-1.71 (0.087)
Panel GARCH-MIDAS (normal)			1.569 (0.117)	0.936 (0.349)	-1.495 (0.135)
Panel GARCH-MIDAS (student-t)				-0.082 (0.934)	-1.613 (0.107)
Panel EWMA					-1.838 (0.066)

Table 5.12: The table of Panel Diebold-Mariano Test results for One-week ahead forecasting horizon with MSE criteria

Table 5.12 and Table 5.13 shows, for forecast horizons of one week. In Table 5.12 there is not a single model significantly better than the other. In Table 5.13 we can see GARCH (normal) and GARCH-MIDAS (normal) are the best ones.

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	-4.729* (0.0)	1.017 (0.309)	-0.261 (0.794)	-3.468* (0.001)	-1.884 (0.06)
Panel GARCH (student-t)		3.123* (0.002)	1.733 (0.083)	-2.414* (0.016)	-1.345 (0.178)
Panel GARCH-MIDAS (normal)			-6.361* (0.0)	-4.68* (0.0)	-1.927 (0.054)
Panel GARCH-MIDAS (student-t)				-3.49* (0.0)	-1.58 (0.114)
Panel EWMA					-0.636 (0.525)

Table 5.13: The table of Panel Diebold-Mariano Test results for One-week ahead forecasting horizon with QLIKE criteria

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	1.998* (0.046)	-0.712 (0.476)	1.333 (0.182)	0.741 (0.459)	-1.819 (0.069)
Panel GARCH (student-t)		-1.446 (0.148)	0.375 (0.708)	-0.377 (0.706)	-1.845 (0.065)
Panel GARCH-MIDAS (normal)			1.856 (0.063)	0.732 (0.464)	-1.726 (0.084)
Panel GARCH-MIDAS (student-t)				-0.392 (0.695)	-1.788 (0.074)
Panel EWMA					-1.982* (0.047)

Table 5.14: The table of Panel Diebold-Mariano Test results for Two-week ahead forecasting horizon with MSE criteria

Table 5.14 and Table 5.15 shows, for forecast horizons of two week. Table 5.14 provides the results with MSE, where the GARCH (student-t) turn out to be better than the GARCH (normal). However in Table 15, where the criteria is QLIKE, the GARCH (normal) is better, than the GARCH (student-t) and the GARCH-MIDAS models are better or equivalent to the others.

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	-3.88* (0.0)	1.258 (0.209)	0.229 (0.819)	-2.363* (0.018)	-1.644 (0.1)
Panel GARCH (student-t)		2.947* (0.003)	1.969* (0.049)	-1.719 (0.086)	-1.233 (0.218)
Panel GARCH-MIDAS (normal)			-3.732* (0.0)	-3.039* (0.002)	-1.746 (0.081)
Panel GARCH-MIDAS (student-t)				-2.372* (0.018)	-1.475 (0.14)
Panel EWMA					-0.46 (0.645)

Table 5.15: The table of Panel Diebold-Mariano Test results for Two-week ahead forecasting horizon with QLIKE criteria

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	1.962* (0.05)	0.12 (0.905)	1.611 (0.107)	1.027 (0.304)	-1.833 (0.067)
Panel GARCH (student-t)		-1.718 (0.086)	0.916 (0.36)	-0.118 (0.906)	-1.855 (0.064)
Panel GARCH-MIDAS (normal)			1.911 (0.056)	0.77 (0.442)	-1.809 (0.071)
Panel GARCH-MIDAS (student-t)				-0.425 (0.671)	-1.834 (0.067)
Panel EWMA					-1.985* (0.047)

Table 5.16: The table of Panel Diebold-Mariano Test results for One-month ahead forecasting horizon with MSE criteria

Finally, Table 5.16 and Table 5.17 shows, for forecast horizons of one month. These tables provide the same conclusions as Table 5.14 and Table 5.15 does, so the QLIKE criteria the GARCH-MIDAS models are better or equivalent to the competitor models.

	Panel GARCH (student-t)	Panel GARCH-MIDAS (normal)	Panel GARCH-MIDAS (student-t)	Panel EWMA	Panel GARCH with CSA
Panel GARCH (normal)	-4.276* (0.0)	0.998 (0.318)	-0.076 (0.939)	-2.19* (0.029)	-1.456 (0.145)
Panel GARCH (student-t)		3.037* (0.002)	1.84 (0.066)	-1.603 (0.109)	-1.039 (0.299)
Panel GARCH-MIDAS (normal)			-3.806* (0.0)	-2.775* (0.006)	-1.511 (0.131)
Panel GARCH-MIDAS (student-t)				-2.14* (0.032)	-1.241 (0.215)
Panel EWMA					-0.135 (0.893)

Table 5.17: The table of Panel Diebold-Mariano Test results for One-month ahead forecasting horizon with QLIKE criteria

Chapter 6

Conclusion

In this chapter, I present the results of my thesis and the conclusions. My main question was whether the Panel GARCH-MIDAS model outperform the standard volatility models. First, I implemented the original models as the presented literature suggested, than I turned to the panel versions. One of my empirical result is the GARCH-MIDAS model's long-term volatility component can be better estimated in the panel version due to the increase of underlying data.

In this thesis, I start with the theoretical background of the volatility models, parameter estimations and simulations. I mainly relied on the research papers for specifying our models. Since I implemented the GARCH-MIDAS model in a two-stage estimation method, so basically we could mix the MIDAS models with other volatility models. I presented the Monte Carlo approach for every single implemented models, to make sure the models are capable to capture the parameters. Next I have introduced our implementation strategy to make models easy to diagnose and to create new models as agile as possible. Following this I have presented the predictive ability tests relied on the literature. Finally, I have shown our results. I have found that our volatility models we can forecast volatility with almost the same accuracy up to a week ahead than the GARCH-MIDAS models are provide a bit better forecasts due to the excess variables. The panel Diebold-Mariano test suggested the GARCH-MIDAS models are better or at least equivalents to the competitor models. However, we could enhance the GARCH-MIDAS models with other specifications of weighting function or select further explanatory variables.

In conclusion, the panel GARCH-MIDAS models are much more suitable for longer forecasting horizon and the variable selection is one of its crucial point. However, for shorter range we could apply the industrial standard EWMA model, since there is only one parameter to be estimated.

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Appendix A

Data

In this appendix, we walkthrough the macroeconomic explanatory variables which we used for modeling and what changes we made. It is worth to mention, that all of our data come from free resources. One of our main objective was to select macroeconomic variables which were previously used in research papers and supplement with our notion. These are the papers which we relied on the selection Conrad and Kleen [2019], Asgharian et al. [2013], Engle et al. [2013], Conrad et al. [2018]. The time series we used for modeling are the following:

- The AAI Investor Sentiment Survey (AAII) measures the percentage of individual investors who are bullish, bearish, and neutral on the stock market for the next months. The series reported on a weekly basis.
<https://www.aaii.com/files/surveys/sentiment.xls>
- Moody's Seasoned BAA Corporate Bond Yield Relative to Yield on 10 Year Treasury Constant Maturity (BAA10Y) is a daily series.
<https://fred.stlouisfed.org/series/BAA10Y>
- The Chicago Fed National Activity Index (CFNAI) is a weighted average of 85 monthly filtered and standardized economic indicators. Whereas positive CFNAI values indicate an expanding US-economy above its historical trend rate, negative values indicate the opposite. Conrad and Kleen [2019]
<https://alfred.stlouisfed.org/series?seid=CFNAI>
- Consumer Price Index for All Urban Consumers: All Items in U.S. City Average (CPIAUCSL) is a measure of the average monthly change in the price for goods and services paid by urban consumers between any two time periods.
<https://alfred.stlouisfed.org/series?seid=CPIAUCSL>
- Case-Shiller U.S. National Home Price Index (CSUSHPINSA) is a monthly index the leading measures of U.S. residential real estate prices, tracking changes in the value of residential real estate nationally.
<https://fred.stlouisfed.org/series/CSUSHPINSA>

- 10-Year Treasury Constant Maturity Rate (DGS10) is a daily percent.
<https://fred.stlouisfed.org/series/DGS10>
- 3-Month Treasury Bill: Secondary Market Rate (DTB3) is a daily percent. Asgharian et al. [2013]
<https://alfred.stlouisfed.org/series?seid=DTB3>
- Housing Starts Total: New Privately Owned Housing Units Started (HOUST) is a monthly unit. Conrad and Kleen [2019]
<https://fred.stlouisfed.org/series/HOUST>
- Industrial Production: Total Index (INDPRO) is a monthly economic indicator that measures real output for all facilities located in the U.S. Conrad and Kleen [2019]
<https://alfred.stlouisfed.org/series?seid=INDPRO>
- M2 Money Stock (M2SL) is a monthly value in units of dollar billions.
<https://fred.stlouisfed.org/series/M2SL>
- Chicago Fed National Financial Conditions Index (NFCI) provides a weekly update on U.S. financial conditions in money markets. Positive values of the NFCI indicate financial conditions that are tighter than average, negative values indicate financial conditions that are looser than average. Conrad and Kleen [2019]
<https://fred.stlouisfed.org/series/NFCI>
- Producer Price Index by Commodity: All Commodities (PPIACO) is a monthly measure of the average change over time in the selling prices received by domestic producers for their output.
<https://alfred.stlouisfed.org/series?seid=PPIACO>
- Unemployment Rate (UNRATE) represents the number of unemployed as a monthly percentage of the labor force. Asgharian et al. [2013]
<https://fred.stlouisfed.org/series/UNRATE>
- CBOE Volatility Index: VIX (VIXCLS) is a daily close index that measures market expectation of near term volatility conveyed by stock index option prices. Conrad and Kleen [2019]
<https://fred.stlouisfed.org/series/VIXCLS>

All of the above time series start in 1997/01/01 and end in 2020/11/01. In order to calculate the inflation, there are two commonly used time series to calculate from, namely the Consumer Price Index (ΔCPI) and Producer Price Index (ΔPPI) differences. The ΔCPI measure the inflation from the changes of prices paid for goods, ΔPPI measure the inflation from the changes of prices received for goods. We see ΔCPI as the true measure of inflation, so it will appear as "INFLATION". We take the differences of M2 Money Stock (henceforth $\Delta M2$), Case-Schiller U.S. National Home Price Index (henceforth ΔCSH), Housing Starts Total (henceforth ΔHOUST) and Industrial

Production (henceforth ΔIP). Asgharian et al. [2013] specified the slope of the yield curve by subtract the 10-Year Treasury Constant Maturity Rate with the 3-Month Treasury Bill, so we used the same transformation to get this variable, which we will refer as *SOYC*. You could spot there were time series which were sampled in a weekly and daily bases, in order to simplify the modeling, we aggregated them to monthly, technically we took their monthly average. The following figure will show the time series of the above described variables:

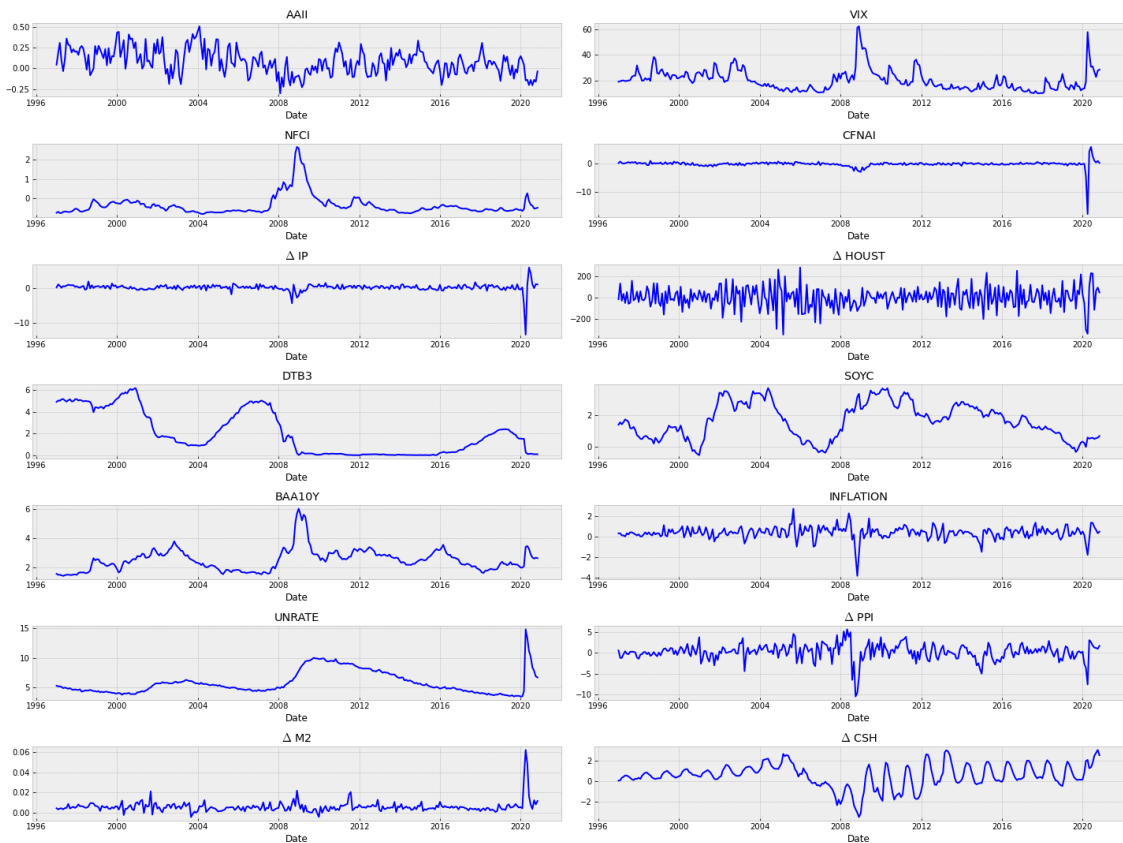


Figure A.1: The time series plots of macroeconomic variables

The stocks we used for modeling are the components of the S&P 500 Index, more technically those who were in the S&P 500 Index at 2020/11/01. The stocks prices start at 1999/12/01 and end at 2020/10/31. All this mean we can observe two stressed period in the modeling, namely the 2007-2008's subprime and the 2020's COVID crisis. The following table will present summary statistics for the macroeconomic variables we used:

	Min.	Max.	Mean	Median	Sd.	Skew.	Kurt
AAII	-0.30	0.51	0.08	0.08	0.15	0.21	-0.30
VIX	10.12	62.25	20.43	19.17	8.27	1.87	5.56
NFCI	-0.80	2.68	-0.36	-0.51	0.51	3.35	13.73
CFNAI	-17.73	5.96	-0.10	-0.01	1.28	-8.89	128.41
Δ IP	-13.26	5.74	0.09	0.14	1.13	-5.80	72.17
Δ HOUST	-343.00	279.00	0.73	-3.00	99.74	-0.26	0.79
DTB3	0.01	6.17	2.00	1.41	1.97	0.61	-1.14
Soyc	-0.53	3.69	1.64	1.62	1.11	0.03	-1.04
BAA10Y	1.45	6.01	2.53	2.50	0.75	1.57	4.73
Inflation	-3.84	2.70	0.36	0.39	0.59	-1.48	10.54
UNRATE	3.50	14.80	5.81	5.10	1.92	1.34	1.72
Δ PPI	-10.50	5.70	0.24	0.30	1.98	-1.28	5.75
Δ M2	-0.01	0.06	0.01	0.01	0.01	5.64	46.91
Δ Csh	-3.53	3.04	0.52	0.51	1.14	-0.60	0.92

Table A.1: The table of summary statistics for the macroeconomic variables.

Appendix B

Implementation code

B.1 base.py

```
import pandas as pd
import numpy as np
from scipy.optimize import minimize
import scipy.stats as stats
from abc import ABCMeta, abstractmethod

class BaseModel(object, metaclass = ABCMeta):
    def __init__(self, plot = True, *args):
        self.plot = plot
        self.args = args

    def transform(self, params, restrictions):
        params_trans = np.zeros(params.shape)
        for i in range(len(params)):
            if restrictions[i] == 'pos':
                params_trans[i] = np.log(params[i])
            elif restrictions[i] == '01':
                params_trans[i] = np.log(params[i]) - np.log(1 - params[i])
            else:
                params_trans[i] = params[i]
        return params_trans

    def transform_back(self, params_trans, restrictions):
        params = np.zeros(params_trans.shape)
        for i in range(len(params_trans)):
```

```

        if restrictions[i] == 'pos':
            params[i] = np.exp(params_trans[i])
        elif restrictions[i] == '01':
            params[i] = 1 / (1 + np.exp(-params_trans[i]))
        else:
            params[i] = params_trans[i]
    return params

def gradient(self, param_trans, restrictions):
    g = np.zeros_like(param_trans)
    for i in range(len(g)):
        if restrictions[i] == '':
            g[i] = 1
        elif restrictions[i] == 'pos':
            g[i] = np.exp(param_trans[i])
        else:
            g[i] = np.exp(param_trans[i]) / np.power(1 + np.exp(param_trans[i]), 2)
    return g

def standard_error(self, optimization, restrictions, y_len):
    grad = self.gradient(
        self.transform_back(optimization.x, restrictions), restrictions)
    variance = optimization.hess_inv.todense() / y_len
    return np.multiply(np.sqrt(np.diag(variance)), grad)

@abstractmethod
def initialize_params(self):
    pass

@abstractmethod
def loglikelihood(self):
    pass

def loglikelihood_trans(self, params_trans, restrictions, X, *y):
    params = self.transform_back(params_trans, restrictions)
    return self.loglikelihood(params, X, *y)

def fit(self, restrictions, X, *y):
    res = minimize(self.loglikelihood_trans,

```

```

        self.transform(self.initialize_params(X), restrictions),
        args = (restrictions, X, *y),
        method = 'l-bfgs-b',
        options = {'disp': False})

self.opt = res
self.optimized_params = self.transform_back(self.opt.x, restrictions)
self.standard_errors = self.standard_error(self.opt, restrictions, len(X))
high = self.optimized_params + stats.norm.ppf(0.975) * self.standard_errors
low = self.optimized_params - stats.norm.ppf(0.975) * self.standard_errors

self.table = pd.DataFrame(data = {'Parameters': self.optimized_params,
                                'Standard_Error': self.standard_errors,
                                '95%_CI_Lower': low,
                                '95%_CI_Higher': high})

if self.plot == True:
    print('Loglikelihood: ', self.opt.fun, '\n')
    print(self.table)

return

```

B.2 volatility.py

```

import numpy as np
import pandas as pd
from base import BaseModel, GarchBase
from stats import loglikelihood_normal, loglikelihood_student_t
from weights import Beta
from helper_functions import create_matrix
from datetime import datetime, timedelta
import time
import scipy.stats as stats

class MIDAS(BaseModel):
    def __init__(self, lag = 22, plot = True, *args):
        self.lag = lag
        self.plot = plot
        self.args = args

    def initialize_params(self, X):

```

```

        self.init_params = np.linspace(1.0, 1.0, int(1.0 + X.shape[1] * 2.0))
    return self.init_params

def model_filter(self, params, x):
    model = params[0]
    for i in range(1, len(x) + 1):
        model += params[2 * i - 1] * Beta().x_weighted(x['X{num}'].format(num = i)),
                                                    [1.0, params[2 * i]])

    return model

def loglikelihood(self, params, X, y):
    X = create_matrix(X, self.lag)
    return np.sum((y - self.model_filter(params, X)) ** 2)

def predict(self, X):
    X = create_matrix(X, self.lag)
    return self.model_filter(self.optimized_params, X)

def simulate(self, params = [2.0, 0.5, 5.0], lag = 12, num = 500):
    y = np.zeros(num)
    x = np.exp(np.cumsum(np.random.normal(0.5, 2, num) / 100))
    alpha, beta, theta = params[0], params[1], params[2]

    for i in range(num):
        if i < lag:
            y[i] = alpha
        else:
            y[i] = alpha + beta * Beta().x_weighted(
                x[i - lag : i][::-1].reshape((1, lag)),
                [1.0, theta])

    return x, y

class GARCH(BaseModel):
    def __init__(self, plot = True, *args):
        self.plot = plot
        self.args = args

    def initialize_params(self, y):

```

```
self.init_params = np.asarray([0.0, 0.05, 0.02, 0.95])
return self.init_params
```

```
def model_filter(self, params, y):
    sigma2 = np.zeros(len(y))
    resid = y - params[0]
    for i in range(len(y)):
        if i == 0:
            sigma2[i] = params[1] / (1 - params[2] - params[3])
        else:
            sigma2[i] = params[1] + params[2] * resid[i - 1] ** 2
            sigma2[i] += params[3] * sigma2[i - 1]
    return sigma2
```

```
def loglikelihood(self, params, y):
    sigma2 = self.model_filter(params, y)
    resid = y - params[0]
    return loglikelihood_normal(resid, sigma2)
```

```
def simulate(self, params = [0.0, 0.2, 0.2, 0.6], num = 500):
    y = np.zeros(num)
    state = np.zeros(num)
    for i in range(num):
        if i == 0:
            state[i] = params[1] / (1 - params[2] - params[3])
        else:
            state[i] = params[1] + params[2] * y[i - 1] * y[i - 1]
            state[i] += params[3] * state[i - 1]
        y[i] = stats.norm.rvs(loc = params[0], scale = np.sqrt(state[i]))
    return y, state
```

```
def predict(self, X):
    return self.model_filter(self.optimized_params, X)
```

```
class TGARCH(BaseModel):
```

```
    def __init__(self, plot = True, *args):
        self.plot = plot
        self.args = args
```

```

def initialize_params(self, y):
    self.init_params = np.asarray([0.1, 0.02, 0.95, 3.75])
    return self.init_params

def model_filter(self, params, y):
    sigma2 = np.zeros(len(y))
    resid = y - params[0]
    for i in range(len(y)):
        if i == 0:
            sigma2[i] = params[1] / (1 - params[2] - params[3])
        else:
            sigma2[i] = params[1] + params[2] * resid[i - 1] ** 2
            sigma2[i] += params[3] * sigma2[i - 1]
    return sigma2

def loglikelihood(self, params, y):
    sigma2 = self.model_filter(params, y)
    resid = y - params[0]
    nu = params[4]
    return loglikelihood_student_t(resid, sigma2, nu)

def simulate(self, params = [0.0, 0.2, 0.2, 0.6, 3.0], num = 500):
    y = np.zeros(num)
    state = np.zeros(num)
    for i in range(num):
        if i == 0:
            state[i] = params[1] / (1 - params[2] - params[3])
        else:
            state[i] = params[1] + params[2] * y[i - 1] * y[i - 1]
            state[i] += params[3] * state[i - 1]
        y[i] = stats.t.rvs(params[4],
                           loc = params[3],
                           scale = np.sqrt(state[i]))
    return y, state

def predict(self, X):
    return self.model_filter(self.optimized_params, X)

class GARCHMIDAS(BaseModel):

```

```

def __init__(self, lag = 22, plot = True, *args):
    self.lag = lag
    self.plot = plot
    self.args = args

def initialize_params(self, X):
    daily_index = np.array([])
    monthly_index = np.array([])
    garch_params = np.array([0.05, 0.05, 0.02, 0.95])
    midas_params = np.array([1.0])
    for i in range(X.shape[1]):
        ratio = X.iloc[:, i].unique().shape[0] / X.shape[0]
        if ratio <= 0.05:
            midas_params = np.append(midas_params, [1.0])
            monthly_index = np.append(monthly_index, i)
        else:
            midas_params = np.append(midas_params, [1.0, 1.0])
            daily_index = np.append(daily_index, i)

    self.monthly = monthly_index
    self.daily = daily_index
    self.init_params = np.append(garch_params, midas_params)
    return self.init_params

def model_filter(self, params, X, y):
    self.g = np.zeros(len(y))
    resid = y - params[0]
    sigma2 = np.zeros(len(y))
    plc = []

    uncond_var = params[1] / (1 - params[2] - params[3])

    per = X.index.to_period('M')
    uniq = np.asarray(per.unique())

    self.tau = np.zeros(len(uniq))

    for t in range(len(uniq)):
        if t == 0:

```

```

        plc.append(np.where((per >= uniq[t].strftime('%Y-%m')) &
                           (per < uniq[t + 1].strftime('%Y-%m')))[0])

    new_d = np.array([])
    elif t != len(uniq) - 1:
        plc.append(np.where((per >= uniq[t].strftime('%Y-%m')) &
                           (per < uniq[t + 1].strftime('%Y-%m')))[0])
        dd = X.iloc[plc[t - 1], self.daily].values
        if len(dd) < self.lag:
            pad = np.zeros((self.lag - len(dd), dd.shape[1]))
            new_d = np.vstack([dd[:, -1], pad]).T
        else:
            new_d = dd[len(dd) - self.lag:][:, -1].T
    else:
        plc.append(np.where(per >= uniq[t].strftime('%Y-%m'))[0])
        dd = X.iloc[plc[t - 1], self.daily].values
        if len(dd) < self.lag:
            pad = np.zeros((self.lag - len(dd), dd.shape[1]))
            new_d = np.vstack([dd[:, -1], pad]).T
        else:
            new_d = dd[len(dd) - self.lag:][:, -1].T

self.tau[t] = params[4] + np.dot(X.iloc[plc[t],
                                       self.monthly].values[0],
                               params[5 : 5 + len(self.monthly)])

for j in range(len(new_d)):
    x = new_d[j].reshape((1, self.lag))
    self.tau[t] += params[5 + len(self.monthly) + j] * Beta().x_weighted(x,
                                   [1.0, params[(5 + len(self.monthly) + self.d

for i in plc[t]:
    if i == 0:
        self.g[i] = uncond_var
        sigma2[i] = self.g[i] * self.tau[t]
    else:
        self.g[i] = uncond_var * (1 - params[2] - params[3])
        self.g[i] += params[2] * ((resid[i-1]** 2) / self.tau[t])

```



```

        self.g[i] += params[3] * self.g[i - 1]
        sigma2[i] = self.g[i] * self.tau[t]

    return sigma2

def loglikelihood(self, params, X, y):
    sigma2 = self.model_filter(params, X, y)
    resid = y - params[0]
    return loglikelihood_normal(resid, sigma2)

def predict(self, X, y):
    return self.model_filter(self.optimized_params, X, y)

class PanelGARCH(BaseModel):
    def __init__(self, plot = True, dist = 'normal', *args):
        self.plot = plot
        self.dist = dist
        self.args = args

    def initialize_params(self, X):
        if self.dist == 'normal':
            self.init_params = np.array([0.4, 0.4])
        elif self.dist == 'student-t':
            self.init_params = np.array([0.4, 0.4, 4.0])
        else:
            raise ValueError("ValueError_exception_thrown")
        return self.init_params

    def model_filter(self, params, X):
        sigma2 = np.zeros_like(X)

        alpha, beta = params[0], params[1]

        uncond_var = np.nanmean(X ** 2, axis = 0)
        nans = X.isna().sum().values
        X = X.values

        for i in range(sigma2.shape[0]):
            for j in range(sigma2.shape[1]):

```

```

        if nans[j] == i:
            sigma2[i][j] = uncond_var[j]
        elif nans[j] < i:
            sigma2[i][j] = uncond_var[j] * (1 - alpha - beta)
            sigma2[i][j] += alpha * (X[i - 1][j] ** 2) + beta * sigma2[i - 1][j]
        else:
            pass
    return sigma2

def loglikelihood(self, params, X):
    sigma2 = self.model_filter(params, X)
    if self.dist == 'normal':
        lls = loglikelihood_normal(X, sigma2).sum()
    elif self.dist == 'student-t':
        lls = loglikelihood_student_t(X, sigma2, params[2]).sum()
    return lls

def simulate(self, params = [0.06, 0.91], num = 100, length = 1000):
    sigma2 = np.zeros((length, num))
    r = np.zeros((length, num))

    alpha, beta = params[0], params[1]

    for t in range(length):
        if t == 0:
            sigma2[t] = 1.0
        else:
            sigma2[t] = 1 - alpha - beta + alpha * (r[t - 1] ** 2)
            sigma2[t] += beta * sigma2[t - 1]
            r[t] = np.random.normal(0.0, np.sqrt(sigma2[t]))
    return sigma2, r

def forecast(self, X, H):
    X_new = X
    X_new.loc[X.shape[0]] = 0

    sigma2 = self.model_filter(self.optimized_params, X_new)
    sigma2 = sigma2 * np.sqrt(H)
    return sigma2[-1]

```

```

class Panel_GARCH_CSA(BaseModel):
    def __init__(self, plot = True, dist = 'normal', *args):
        self.plot = plot
        self.dist = dist
        self.args = args

    def initialize_params(self, X):
        if self.dist == 'normal':
            self.init_params = np.array([0.1, 0.5, 0.5])
        elif self.dist == 'student-t':
            self.init_params = np.array([0.1, 0.5, 0.5, 4.0])
        return self.init_params

    def model_filter(self, params, X):
        c = np.zeros(X.shape[0])
        sigma2 = np.zeros_like(X)

        phi, alpha, beta = params[0], params[1], params[2]

        uncond_var = np.nanmean(X ** 2, axis = 0)
        nans = X.isna().sum().values
        X = X.values

        for i in range(sigma2.shape[0]):
            if i == 0:
                c[i] = 1
            else:
                c[i] = (1 - phi) + phi * np.nanstd(X[i-1] / (np.sqrt(sigma2[i-1])
                    * c[i-1]), ddof = 1)

            for j in range(sigma2.shape[1]):
                if nans[j] == i:
                    sigma2[i][j] = uncond_var[j]
                elif nans[j] < i:
                    sigma2[i][j] = uncond_var[j] * (1 - alpha - beta)
                    sigma2[i][j] += alpha * ((X[i-1][j] / (np.sqrt(sigma2[i-1][j])
                    sigma2[i][j] += beta * sigma2[i-1][j])
                else:
                    pass

```

```

return sigma2, c

def loglikelihood(self, params, X):
    sigma2, _ = self.model_filter(params, X)
    if self.dist == 'normal':
        lls = loglikelihood_normal(X, sigma2).sum()
    elif self.dist == 'student-t':
        lls = loglikelihood_student_t(X, sigma2, params[3]).sum()
    return lls

def simulate(self, params = [0.1, 0.2, 0.6], num = 100, length = 500):
    c = np.zeros(length)
    sigma2 = np.zeros((length, num))
    ret = np.zeros((length, num))

    phi, alpha, beta = params[0], params[1], params[2]

    for t in range(length):
        if t == 0:
            c[t] = 1.0
            sigma2[t] = 1.0
        else:
            c[t] = (1 - phi) + phi * np.nanstd(ret[t - 1] / (np.sqrt(sigma2[t - 1])
                * c[t - 1]), ddof = 1)

            mu = np.mean(ret[:t] ** 2, axis = 0)
            sigma2[t] = mu * (1 - alpha - beta)
            sigma2[t] += alpha * (ret[t - 1] / (np.sqrt(sigma2[t - 1]) * c[t - 1])) ** 2
            sigma2[t] += beta * sigma2[t - 1]

            ret[t] = stats.norm.rvs(loc = 0.0, scale = np.sqrt(sigma2[t]))

    return ret, sigma2, c

def forecast(self, params, X, H = 1):
    X_new = X
    X_new.loc[X.shape[0]] = 0

    sigma2, _ = self.model_filter(params, X_new)
    sigma2 = sigma2 * np.sqrt(H)

```

```
return sigma2[-1]
```

```
class Panel_MIDAS(BaseModel):
```

```
def __init__(self, lag = 12, plot = True, exp = True, *args):
```

```
    self.lag = lag
```

```
    self.plot = plot
```

```
    self.exp = exp
```

```
    self.args = args
```

```
def initialize_params(self, X):
```

```
    self.init_params = np.linspace(1, 1, int(1.0 + X.shape[1] * 2.0))
```

```
    return self.init_params
```

```
def model_filter(self, params, X):
```

```
    X = create_matrix(X, self.lag)
```

```
    model = params[0]
```

```
    for i in range(1, len(X) + 1):
```

```
        model += params[2 * i - 1] * Beta().x_weighted(X['X{num}'].format(num =  
                                                    [1.0, params[2 * i]]))
```

```
    if self.exp == True:
```

```
        return np.exp(model)
```

```
    else:
```

```
        return model
```

```
def loglikelihood(self, params, X, y):
```

```
    try:
```

```
        y_len, y_col = y.shape
```

```
    except:
```

```
        y_len, y_col = y.shape[0], 1
```

```
    y_nan = y.isna().sum().values
```

```
    self.tau_t = np.zeros(y_len)
```

```
    tau = self.model_filter(params, X)
```

```
    T = X.shape[0]
```

```
    j = 0
```

```
    for i in range(T - 1):
```

```
        if i == 0:
```

```
            index = y[y.index < X.index[i + 1]].index
```

```

    else:
        index = y[(y.index >= X.index[i]) & (y.index < X.index[i + 1])].index

        mat = np.linspace(tau[i], tau[i], index.shape[0])
        self.tau_t[j : j + index.shape[0]] = mat
        j += index.shape[0]

lls = 0
for i in range(y_col):
    if y_nan[i] >= y_len:
        lls += 0
    else:
        lls += loglikelihood_normal(y.iloc[y_nan[i]:, i].values,
                                    self.tau_t[y_nan[i]:])

return lls

def simulate(self, params = [0.1, 0.3, 4.0], num = 500, K = 12, panel = 100):
    X = np.zeros(num)
    tau = np.zeros(num)
    r = np.zeros((num * 22, panel))
    j = 0
    month = []
    m_dates = []
    y_dates = []

    for t in range(num):
        if t == 0:
            X[t] = np.random.normal()
        else:
            X[t] = 0.9 * X[t - 1] + np.random.normal()

    for t in range(1, num + 1):
        if t < K + 1:
            tau[t - 1] = np.exp(params[0])
            tau[t - 1] += params[1] * Beta().x_weighted(X[:t][::-1].reshape((1, X[:t].
                                                                              [1.0, par

        else:
            tau[t - 1] = np.exp(params[0])
            tau[t - 1] += params[1] * Beta().x_weighted(X[t - K : t][::-1].reshape((

```

```

[1.0, params[2]])

r[(t - 1) * 22 : t * 22] = np.random.normal(scale = np.sqrt(tau[t - 1])
                                             size = (22, panel))

for i in range(num):
    month.append(i % 12)

for i in month:
    if i == 0:
        j += 1
        m_dates.append(datetime(2010 + j, 1, 1))
    else:
        m_dates.append(datetime(2010 + j, 1 + i, 1))

for i in m_dates[:-1]:
    for j in range(22):
        y_dates.append(i + timedelta(j))

y = pd.DataFrame(data = r[:-22], index = y_dates)
X = pd.DataFrame(data = X, index = m_dates)

return X, y, tau

def create_sims(self, number_of_sims = 500, length = 100,
                K = 12, params = [0.1, 0.3, 4.0], panel = 200):
    lls = np.zeros(number_of_sims)
    b0, b1 = np.zeros(number_of_sims), np.zeros(number_of_sims)
    th, runtime = np.zeros(number_of_sims), np.zeros(number_of_sims)

    for i in range(number_of_sims):
        np.random.seed(i)
        X, y, _ = self.simulate(params = params, num = length, K = K, panel = p
        start = time.time()
        self.fit(['pos', 'pos', 'pos'], X, y)
        runtime[i] = time.time() - start
        lls[i] = self.opt.fun
        b0[i], b1[i] = self.optimized_params[0], self.optimized_params[1],

```

```

        th[i] = self.optimized_params[2]
        print("{}st iteration's runtime: {}sec.\n".format(i + 1, round(runtime[i],

return pd.DataFrame(data = {'LogLike': lls,
                            'Beta0': b0,
                            'Beta1': b1,
                            'Theta': th})

class Panel_GARCH_MIDAS():
    def __init__(self, lag = 12, plot = True, exp = True, *args):
        self.lag = lag
        self.exp = exp
        self.plot = plot
        self.args = args

    def fit(self, restriction_midas, restriction_garch, X, y):
        self.midas = Panel_MIDAS(lag = self.lag, plot = self.plot, exp = self.exp)
        if self.plot == True:
            print('Estimated parameters for the MIDAS equation:\n')
        else:
            pass
        self.midas.fit(restriction_midas, X, y)

        y_hat = self.calculate_y_hat(y, self.midas.tau_t)

        self.garch = Panel_GARCH(plot = self.plot)
        if self.plot == True:
            print('\nEstimated parameters for the GARCH equation:\n')
        else:
            pass
        self.garch.fit(restriction_garch, y_hat)

    def calculate_y_hat(self, y, tau):
        y_hat = np.zeros_like(y)

        for i in range(y.shape[0]):
            for j in range(y.shape[1]):
                y_hat[i][j] = y.iloc[i, j] / np.sqrt(tau[i])

```



```
y_hat = pd.DataFrame(data = y_hat, index = y.index, columns = y.columns)
```

```
return y_hat
```

```
def simulate(self, midas_params = [0.1, 0.3, 4.0],
            garch_params = [0.06, 0.8], num = 500, K = 12, panel = 100):
    beta0, beta1, theta = midas_params[0], midas_params[1], midas_params[2]
    alpha, beta = garch_params[0], garch_params[1]
    X = np.zeros(num)
    tau = np.zeros(num)
    r = np.zeros((num * 22, panel))
    g = np.zeros((num * 22, panel))
    j = 0
    month = []
    m_dates = []
    y_dates = []

    for t in range(num):
        if t == 0:
            X[t] = np.random.normal()
        else:
            X[t] = 0.9 * X[t - 1] + np.random.normal()

    for t in range(1, num + 1):
        if t < K + 1:
            tau[t - 1] = np.exp(beta0 +
                                beta1 * Beta().x_weighted(X[:t][::-1].reshape((1, X[:t]
                                                                              [1.0, theta])))
        else:
            tau[t - 1] = np.exp(beta0 +
                                beta1 * Beta().x_weighted(X[t - K : t][::-1].reshape((1
                                                                              [1.0, theta])))

    for i in range((t - 1) * 22, t * 22):
        if i == 0:
            g[i] = np.ones(panel)
        else:
            g[i] = (1 - alpha - beta)
            g[i] += alpha * (r[i - 1] ** 2) / tau[t - 1] + beta * g[i - 1]
```

```

        r[i] = np.random.normal(scale = np.sqrt(g[i] * tau[t - 1]), size = panel)

for i in range(num):
    month.append(i % 12)

for i in month:
    if i == 0:
        j += 1
        m_dates.append(datetime(2010 + j, 1, 1))
    else:
        m_dates.append(datetime(2010 + j, 1 + i, 1))

for i in m_dates[:-1]:
    for j in range(22):
        y_dates.append(i + timedelta(j))

y = pd.DataFrame(data = r[:-22], index = y_dates)
X = pd.DataFrame(data = X, index = m_dates)

return X, y, tau, g

def create_sims(self, number_of_sims = 500, length = 100,
                K = 12, midas_params = [0.1, 0.3, 4.0], garch_params = [0.06, 0.8]):
    b0, b1 = np.zeros(number_of_sims), np.zeros(number_of_sims)
    th, al = np.zeros(number_of_sims), np.zeros(number_of_sims)
    bt, runtime = np.zeros(number_of_sims), np.zeros(number_of_sims)

    for i in range(number_of_sims):
        np.random.seed(i)
        X, y, -, - = self.simulate(midas_params = midas_params,
                                garch_params = garch_params,
                                num = length, K = K, panel = 100)

        start = time.time()
        self.fit(['pos', 'pos', 'pos'], ['01', '01'], X, y)
        runtime[i] = time.time() - start
        b0[i], b1[i] = self.midas.optimized_params[0], self.midas.optimized_params[1]
        th[i], al[i] = self.midas.optimized_params[2], self.garch.optimized_params[0]
        bt[i] = self.garch.optimized_params[1]

```

```

        print("{}st iteration's runtime: {}sec.\n".format(i + 1, round(runtime

return pd.DataFrame(data = {'Beta0': b0,
                             'Beta1': b1,
                             'Theta': th,
                             'Alpha': al,
                             'Beta': bt})

def forecast(self, y, H = 5, plotting = True):
    from pandas.tseries.offsets import BDay
    import matplotlib.pyplot as plt
    forecast = np.zeros(H)
    mu = np.mean(y ** 2)
    alpha = self.garch.optimized_params[0]
    beta = self.garch.optimized_params[1]
    y_hat = y / self.midas.tau_t
    sigma2 = self.garch.model_filter(self.garch.optimized_params, y_hat)

    for i in range(1, H + 1):
        forecast[i - 1] = (mu * (1 - (alpha + beta) ** (i - 1))
                           + sigma2[-1] * (alpha + beta) ** (i - 1)) * self.midas

    forc = np.zeros(len(y) + H)
    forc[:-H] = sigma2 * self.midas.tau_t
    forc[-H:] = forecast

    if isinstance(y, pd.core.series.Series) or isinstance(y, pd.core.frame.DataFrame):
        index = []
        for i in range(len(y) + H):
            if i < len(y):
                index.append(y.index[i])
            else:
                index.append(y.index[-1] + BDay(i - len(y.index) + 1))

    forecasted_series = pd.Series(data = forc, index = index)
    if plotting == True:
        plt.figure(figsize = (15, 5))
        plt.plot(forecasted_series[forecasted_series.index <=

```

```

                pd.to_datetime(y.index[-1]), 'g')
plt.plot(forecasted_series[forecasted_series.index >
                pd.to_datetime(y.index[-1])], 'r')
plt.title("Volatility Prediction for the next {} days".format(H))
plt.tight_layout()
plt.show()

else:
    forecasted_series = forc

return forecasted_series

class EWMA(BaseModel):
    def __init__(self, plot = True, lam = 0.94, *args):
        self.plot = plot
        self.lam = 0.94
        self.args = args

    def initialize_params(self, y):
        self.init_params = np.array([self.lam])
        return self.init_params

    def model_filter(self, params, y):
        T = y.shape[0]
        sigma2 = np.zeros(T)
        lamb = params

        for t in range(T):
            if t == 0:
                sigma2[t] = 1.0
            else:
                sigma2[t] = lamb * sigma2[t - 1] + (1 - lamb) * y[t - 1] ** 2
        return sigma2

    def loglikelihood(self, params, y):
        sigma2 = self.model_filter(params, y)
        return loglikelihood_normal(y, sigma2)

    def simulate(self, lamb, T):
        sigma2 = np.zeros(T)

```

```

ret = np.zeros(T)

for t in range(T):
    if t == 0:
        sigma2[t] = 1.0
    else:
        sigma2[t] = lamb * sigma2[t - 1] + (1 - lamb) * ret[t - 1] ** 2
    ret[t] = np.random.normal(scale = np.sqrt(sigma2[t]))

return ret, sigma2

class PanelEWMA(BaseModel):
    def __init__(self, plot = True, lam = 0.94, *args):
        self.plot = plot
        self.lam = 0.94
        self.args = args

    def initialize_params(self, y):
        self.init_params = np.array([self.lam])
        return self.init_params

    def model_filter(self, params, y):
        T = y.shape[0]
        sigma2 = np.zeros(T)
        lamb = params

        for t in range(T):
            if t == 0:
                sigma2[t] = 1.0
            else:
                sigma2[t] = lamb * sigma2[t - 1] + (1 - lamb) * y[t - 1] ** 2
        return sigma2

    def loglikelihood(self, params, y):
        lls = 0

        for i in range(y.shape[1]):
            idx = np.where(np.isnan(y.iloc[:, i]) == False)[0]
            sig = self.model_filter(params, y.iloc[idx, i].values)

```

```

        if len(sig) == 0:
            lls += 0
        else:
            lls += loglikelihood_normal(y.iloc[idx, i].values, sig)
    return lls

def forecast(self, y):
    row_nul = pd.DataFrame([[0]*y.shape[1]], columns = y.columns)
    y = y.append(row_nul)
    forecast = np.zeros(len(y.columns))
    for i in range(ret_mat.shape[1]):
        idx = np.where(np.isnan(y.iloc[:, i]) == False)[0]
        if len(idx) == 0:
            forecast[i] = np.nan
        else:
            sig = model.model_filter(model.optimized_params, y.iloc[idx, i].values)
            forecast[i] = sig[-1]
    return forecast

def simulate(self, lamb = 0.94, T = 500, num = 100):
    sigma2 = np.zeros((T, num))
    r = np.zeros((T, num))

    for t in range(T):
        if t == 0:
            sigma2[t] = 1.0
        else:
            sigma2[t] = lamb * sigma2[t - 1] + (1 - lamb) * r[t - 1] ** 2
            r[t] = np.random.normal(0.0, np.sqrt(sigma2[t]), size = num)
    return r, sigma2

```

B.3 weights.py

```

import numpy as np
from scipy.stats import beta as b
from abc import ABCMeta, abstractmethod

class WeightMethod(object, metaclass = ABCMeta):
    def __init__(self, *args):

```

```

        self.args = args

    @abstractmethod
    def weights(self):
        pass

    def x_weighted(self, x, params, arg = False):
        if arg == False:
            try:
                w = self.weights(params, x.shape[1])
            except:
                w = self.weights(params, 1)
        else:
            try:
                w = self.weights(params, x.shape[0])
            except:
                w = self.weights(params, 1)
        return np.matmul(x, w)

class Beta(WeightMethod):
    def weights(self, params, nlags):
        eps = 1e-6
        x = np.linspace(eps, 1 - eps, nlags)
        beta_vals = b.pdf(x, params[0], params[1])
        beta_vals /= np.sum(b.pdf(x, params[0], params[1]))
        return beta_vals

class ExpAlmon(WeightMethod):
    def weights(self, params, nlags):
        ith = np.arange(1, 1 + nlags)
        almon_vals = np.exp(params[0] * ith + params[1] * ith ** 2)
        almon_vals /= np.sum(np.exp(params[0] * ith + params[1] * ith ** 2))
        return almon_vals

class Exp(WeightMethod):
    def weights(self, params, nlags):
        ith = np.arange(1, 1 + nlags)
        ew = params ** ith / np.sum(params ** ith)
        return ew

```

B.4 stats.py

```
import numpy as np
from scipy.special import gammaln
from scipy.stats import t
import pandas as pd

def loglikelihood_normal(resid, sigma2):
    lls = -0.5 * (np.log(2*np.pi) + np.log(sigma2) + resid ** 2 / sigma2)
    return np.sum(-lls) / len(resid)

def loglikelihood_student_t(resid, sigma2, nu):
    lls = gammaln((nu + 1) / 2) - gammaln(nu / 2) - np.log(np.pi * (nu - 2)) / 2
    lls -= 0.5 * np.log(sigma2)
    lls -= ((nu + 1) / 2) * (np.log(1 + (resid ** 2) / (sigma2 * (nu - 2))))
    return np.sum(-lls) / len(resid)

def squared_return(df):
    r_t = np.log(df.Close) - np.log(df.Close.shift(1))
    volatility = r_t ** 2
    df['Squared_Return'] = volatility.fillna(0)
    return df

def parkinson_high_low(df):
    high_low_t = np.log(df.High) - np.log(df.Low)
    volatility = (high_low_t ** 2) / (4 * np.log(2))
    df['High_Low_Est'] = volatility.fillna(0)
    return df

def dm_test(act, pred1, pred2, h = 1, degree = 0, plot = False):
    e1_lst, e2_lst, d_lst = [], [], []

    act_lst = np.asarray(act)
    pred1_lst = np.asarray(pred1)
    pred2_lst = np.asarray(pred2)

    def family_of_loss_func(actual, predicted, degree):
```



```

if degree == -2:
    # QLIKE
    loss = actual / predicted - np.log(actual / predicted) - 1
elif degree == -1:
    loss = predicted - actual + actual * np.log(actual / predicted)
else:
    # MSE if degree = 0
    loss = (np.sqrt(actual) ** (2 * degree + 4)
            - predicted ** (degree + 2)) / ((degree + 1) * (degree + 2))
    loss -= (1 / (degree + 1)) * (predicted ** (degree + 1)) * (actual - pr
return loss

T = float(len(act_lst))
for a, p1, p2 in zip(act_lst, pred1_lst, pred2_lst):
    e1_lst.append(family_of_loss_func(a, p1, degree))
    e2_lst.append(family_of_loss_func(a, p2, degree))

for e1, e2 in zip(e1_lst, e2_lst):
    d_lst.append(e1 - e2)

d_mean = np.mean(d_lst)

def autocovariance(Xi, N, k, Xs):
    autoCov = 0
    T = float(N)
    for i in np.arange(0, N - k):
        autoCov += ((Xi[i + k]) - Xs) * (Xi[i] - Xs)
    return autoCov / T

gamma = []

for lag in range(0, h):
    gamma.append(autocovariance(d_lst, len(d_lst), lag, d_mean))

V_d = (gamma[0] + 2 * np.sum(gamma[1:])) / T
DM_stat = d_mean * V_d ** -0.5

p_value = 2 * t.cdf(-np.abs(DM_stat), df = T - 1)

```

```

if plot == True:
    print('DM=', DM_stat, '\nDM_p-value', p_value)
return DM_stat, p_value

def family_of_loss_func(actual, predicted, degree):
    if degree == -2:
        # QLIKE
        loss = actual / predicted - np.log(actual / predicted) - 1
    elif degree == -1:
        loss = predicted - actual + actual * np.log(actual / predicted)
    else:
        # MSE if degree = 0
        loss = (np.sqrt(actual) ** (2 * degree + 4)
                - predicted ** (degree + 2)) / ((degree + 1) * (degree + 2))
        loss -= (1 / (degree + 1)) * (predicted ** (degree + 1)) * (actual - predicted)
    return loss

def panel_DM(act, pred1, pred2, degree = 0):
    l1 = family_of_loss_func(act, pred1, degree)
    l2 = family_of_loss_func(act, pred2, degree)
    d12 = l1 - l2
    d12n = np.nansum(d12, axis = 1)
    n = np.sum(~np.isnan(d12), axis = 1)
    T = d12.shape[0]
    nT = np.sum(~np.isnan(d12))
    hat_d12 = np.nansum(d12, axis = 1) / np.sum(~np.isnan(d12), axis = 1)
    R12 = np.sqrt(n) * hat_d12
    hat_R0 = np.nansum(R12) / T
    hat_R1 = np.nansum(R12[1:]) / (T - 1)
    hat_R11 = np.nansum(R12[: -1]) / (T - 1)
    g0 = np.nansum((R12 - hat_R0) * (R12 - hat_R0)) / T
    g1 = 2 * np.nansum((R12[1:] - hat_R11) * (R12[: -1] - hat_R11)) / (T - 1)
    sig = np.sqrt(g0 + g1)
    DM = np.nansum(d12) / (np.sqrt(nT) * sig)
    p_value = 2 * t.cdf(-np.abs(DM), df = nT - 1)
    return DM, p_value

```

B.5 helper functions.py

```
import pandas as pd

def create_lagged_variable(data, name, lag):
    new_df = pd.DataFrame(data = {name: data})
    for i in range(lag):
        new_df['Lag_{number}'.format(number = i + 1)] = new_df[name].shift(i).fillna(0)
    return new_df

def create_matrix(data, lag):
    X = {}

    for i in range(1, len(data.columns) + 1):
        if isinstance(lag, int) or isinstance(lag, float):
            X['X{num}'.format(num = i)] = create_lagged_variable(data.iloc[:, i - 1],
                                                                data.columns[i - 1], lag).iloc[:, -lag:]
        elif isinstance(lag, list) or isinstance(lag, np.ndarray):
            X['X{num}'.format(num = i)] = create_lagged_variable(data.iloc[:, i - 1],
                                                                data.columns[i - 1], lag[i - 1]).iloc[:, -lag[i - 1]:]
        else:
            raise ValueError("ValueError_exception_thrown")
    return X
```