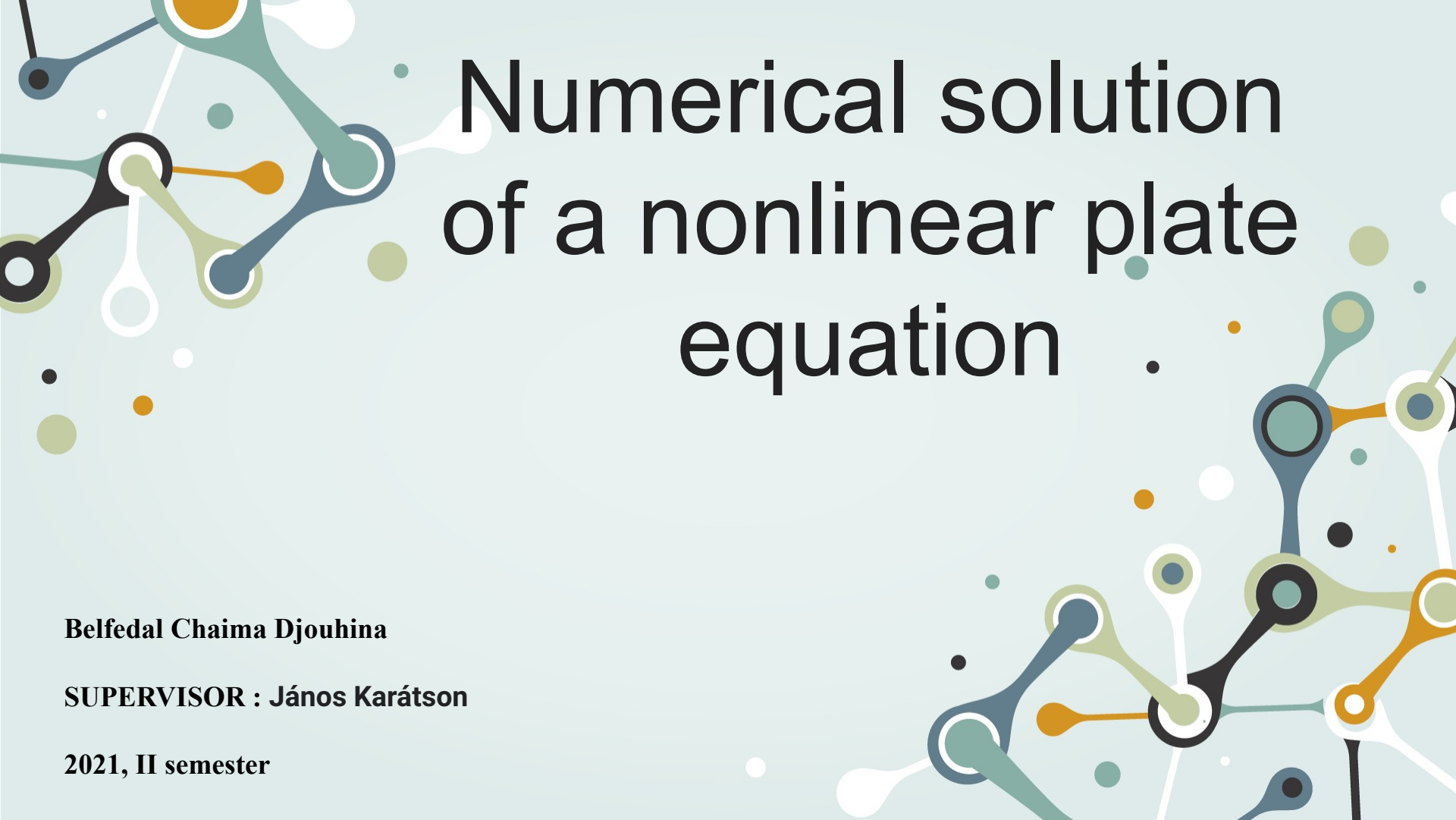




Directed Studies 1



Numerical solution of a nonlinear plate equation

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PURPOSE OF PROJECT

- Understand the weak form of the nonlinear plate equation (a 4th order PDE) and prove that it has a unique weak solution.
- Theory for the numerical solution: construction and proof of convergence. It consists of finite element discretization, Newton linearization and conjugate gradient method.



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The PDE model :

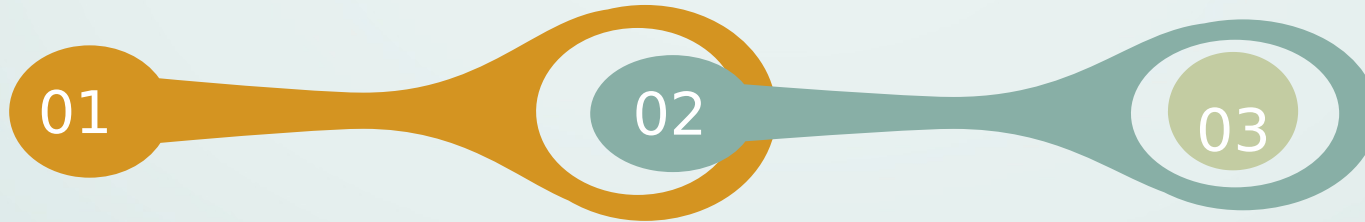
Elasto-plastic
bending of clamped
plates

Weak formulation :

Prove existence and
uniqueness

Theory for the numerical solution :

1. Apply a finite element discretization
2. Apply a Newton iteration (so-called "outer iteration")
3. Apply the PCG method("inner iteration"),



The PDE :

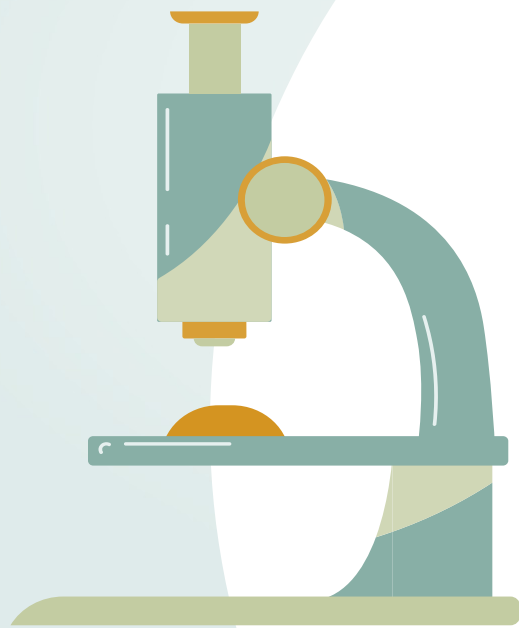
Elasto-plastic bending of a clamped thin plane plate Ω is described by a fourth order nonlinear Dirichlet boundary value problem .

The formulation of the problem is the following :

$$\left\{ \begin{array}{l} \frac{\partial^2}{\partial x^2} \left(\bar{g}(E(D^2u)) \left(\frac{\partial^2 u}{\partial x^2} + \frac{1}{2} \frac{\partial^2 u}{\partial y^2} \right) \right) + \frac{\partial^2}{\partial x \partial y} \left(\bar{g}(E(D^2u)) \left(\frac{\partial^2 u}{\partial x \partial y} \right) \right) \\ \quad + \frac{\partial^2}{\partial y^2} \left(\bar{g}(E(D^2u)) \left(\frac{\partial^2 u}{\partial y^2} + \frac{1}{2} \frac{\partial^2 u}{\partial x^2} \right) \right) = \alpha(x) \\ u|_{\partial\Omega} = \frac{\partial u}{\partial \nu} |_{\partial\Omega} = 0 \end{array} \right.$$



This problem is written briefly as
where the scalar function satisfies the condition
with suitable constants independent of the variable .
where





The weak formulation of

The weak formulation of the problem : find u such that

For regular functions v , the weak formulation is obtained via multiplying our problem by v , integration and the divergence theorem. In this way we have

Instead of (1). The latter can be obtained from here by defining

And $a(u, v)$, which yields that

Prove the existence and uniqueness of the weak

Theorem 1:

solution :

Let H be a real Hilbert space and let the operator F have the following properties:

- (i) F has a bihemicontinuous symmetric Gateaux derivative
- (ii) there exists a constant c such that

Then for any $f \in H$ the equation $F(u) = f$ has a unique solution

Prove the existence and

Uniqueness of the weak

Remark 1:

Let F have the form :

solution :

where the scalar function satisfies the condition

Then (2) defines an operator which has a bihemicontinuous symmetric Gateaux derivative satisfying

Proposition 1 : The elasto-plastic bending problem of a clamped plate has a unique weak solution

Proof :

For any matrices let us introduce the following notations:

we verify directly via Remark 1 for the operator \mathcal{L} ,

where

Using the weak form and previously notations, we have

=

=

The obtained form of F is a special case of (2) with

hence Theorem 1 can be applied.

Finite element

Galerkin's method for nonlinear operator equations : discretization:

Let H be a real Hilbert space and a given operator, which is uniformly monotone and Lipschitz continuous.

Consider the operator equation (1)

where T . The equation (1) admits a unique solution.

Let us write the equation (1) in its equivalent variational forms involving test functions :

Let The approximate solution u_h is defined by the subspace equation

(2)

The equation (2) admits a unique solution.

The coefficients of the expansion u_h can be obtained as follows. We set

Let us introduce the real functions (

and let c_j , Now put these functions together in (c) so the coefficients c_j of u_h can be obtained by solving the nonlinear algebraic system of equations

(c) =



("Nonlinear Céa's lemma") :

For the Galerkin solution ,the quasi-optimality relation

}

holds true



Example:

Consider the problem :

where and due to the assumptions on there exists a unique weak solution , that is,

Let be some finite element subspace , Then the approximate solution satisfies the subspace equation :

and the coefficients can be obtained by solving the nonlinear system of algebraic equations :

$$\mathcal{A}(c) = \mathcal{B}$$

where and

Here, \mathcal{A} inherits the uniform monotonicity and Lipschitz continuity of f , so unique solvability of this system follows from the theorem on the Galerkin method. Further, the nonlinear Céa's lemma holds true

Newton linearization :

Theorem 1:

Let X and Y be Banach spaces and let f be Fréchet differentiable, then assume that

f' is Lipschitz continuous with constant L . If $\|f'(x_0)^{-1}\| \leq M$, then the iteration

satisfies

(1)

(2) If $\|f'(x_0)^{-1}\| \leq M$ is such that

then

m



Theorem 2: Assume conditions of Theorem 1 and let y be the solution of the equation
let ϵ be arbitrary

Then :

Decreases monotonically and locally quadratically i.e after a suitable index

and

where

Example :

Consider the finite element solution :

and define the operator as

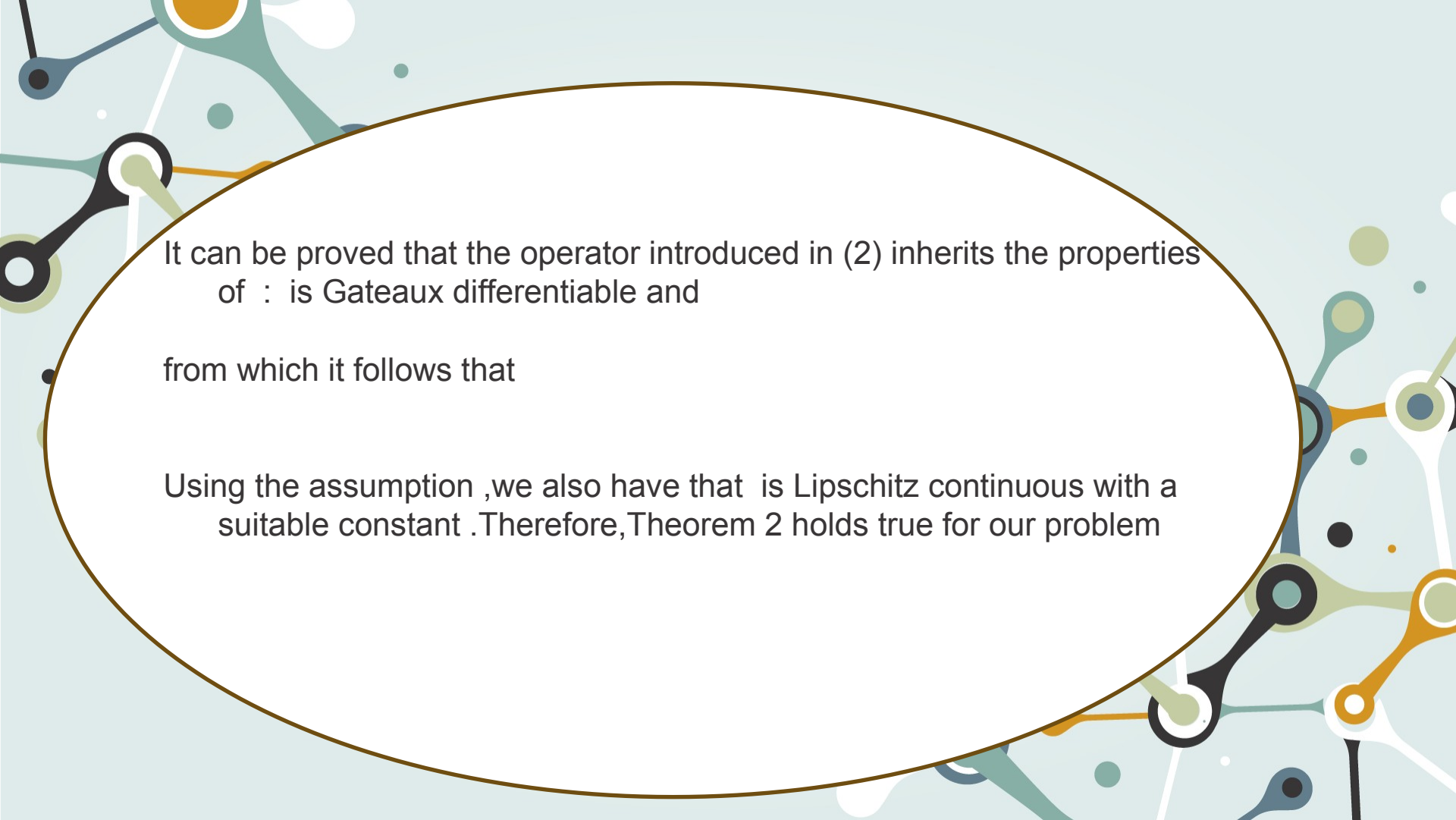
The Newton iteration requires more differentiability, so we need more conditions on f .

Assumption (N) :

and the Jacobians are symmetric and

there are such that :

Further, assume that is Lipschitz continuous



It can be proved that the operator introduced in (2) inherits the properties of \mathcal{A} : is Gateaux differentiable and

from which it follows that

Using the assumption ,we also have that \mathcal{A} is Lipschitz continuous with a suitable constant .Therefore,Theorem 2 holds true for our problem

Inner-outer iterations

1. Assumptions:

Let Assumptions (N) hold. Let V be a finite dimensional subspace with the inner product and let

and

Denote by u the solution of

The operator F is Gâteaux differentiable and its derivative is given by

The operator F' inherits the Lipschitz continuity of F , Let L denote the Lipschitz constant of F' .

2. Construction:

Let $\{x_n\}$ and define the sequence as follows :

(a) The outer iteration defines the sequence
$$x_{n+1} = \dots \quad (2.1)$$

where x_n is the numerical solution of :

Further, $\{x_n\}$ is constant satisfying
$$\dots \quad (2.3)$$

(b) To determine x^* in (2.2), the inner iteration defines a sequence

using a preconditioned conjugate gradient method. Here we have :

Let

Then we consider the preconditioned form of (2.2) :

Finally, for which

with and

Theorem 3:

Let Assumptions be satisfied. Then construction yields the following convergence results :

(1) The outer iteration (\cdot) satisfies (\cdot) monotonically

with speed depending on the sequence (\cdot) up to locally quadratic order.

Namely, if (\cdot) , then the convergence is linear.

Further, if

with some constant (\cdot) , then the convergence is locally of order

yielding also the convergence estimate of weak order

with suitable constants



(2) there holds

$\text{cond}(\dots)$

And, accordingly, the inner iteration satisfies

Therefore, the number of inner iterations for the n th outer step is at most

with





Let ϕ be a real function that is in the variable ϕ , and there exists ϵ such that

If these conditions hold for “ ϵ ”, then the conditions of Theorem 3 are satisfied for the plate problem

Hence the inner-outer method works for our model problem.

THANK YOU

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